

# **JT632xA Series Programmable Electronic Load Users' Manual**

JT6321A/JT6322A/JT6323A/

JT6324A/JT6325A/JT6326A

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# Chapter One: Introduction

JT632xA series electronic load is functioned with 500KHz high-speed synchronous sampling, DSP technology, powerful transient test and multi-aspect intelligence analysis. All these four functions are fully integrated into automatic test function, which makes JT632xA series electronic load very suitable for testing power supply when produced in large quantity. Besides, JT632xA series electronic load also possesses the features of current rising slew rate programmable, high-speed dynamic loading and programmable list function, which makes JT632xA series electronic load satisfying most of R&D requirements. Moreover, JT632xA series load's synchronous control function can satisfy the synchronous loading requirements of multi-output power supply and satisfy single-output power supply requirement for big power.

## Features:

- ★ Max. power: 300W; Max. current: 60A; Max. voltage: 500V.
- ★ Support up to 16 loads synchronous loading & dynamic test, fit for testing multi-output power supply.
- ★ Support up to 16 loads parallel mode for high power.
- ★ 500KHz synchronous sampling with 10Hz, 10uA, 0.1mV stable resolution.
- ★ Support the measurement of ripple voltage/current ( $V_{pp}/I_{pp}$ ), peak voltage/current ( $V_{p+}/I_{p+}$ ) and valley voltage/current ( $V_{p-}/I_{p-}$ ).
- ★ The current rising and falling slew rate are both programmable.
- ★ Support CC, CV, CP & CR mode.
- ★ Support accurately simulating LED electronic load loading.
- ★ Support CP & CR mode when in CV/CC source and support CV/CC source detecting and matching when in CR mode.
- ★ Support up to 50KHz dynamic loading mode and peak voltage ( $V_{p+}$ ) and valley voltage ( $V_{p-}$ ) measurement.
- ★ Support over current protection test (OCP) and maximum power point capture (Pmax).
- ★ Support load effect measurement.
- ★ Support high-speed dynamic frequency sweep function.
- ★ Support timing measurement.
- ★ Support over voltage protection test (OVP).
- ★ Built-in waveform generator. In list mode, different waveforms can be simulated.
- ★ Support short-circuit analog function.
- ★ Support automatic test (A-test) alone.
- ★ Support battery resistance and battery capacity test.
- ★ Support remote sensing.
- ★ Support Von and Voff function.
- ★ Shortcut supports 20 groups of data storage and read.
- ★ High-luminance & full view graphic dot matrix screen.
- ★ Over current, over voltage, over power, over temperature, polarity reversed protection
- ★ Intelligent fan system. Fan will be automatically initiated according to the temperature.
- ★ Support external trigger input and output.
- ★ Standard RS232 interface.
- ★ Support current waveform output monitoring.
- ★ Standard SCPI protocol.

## Chapter Two: Technical Data

### 2.1. Technical Data

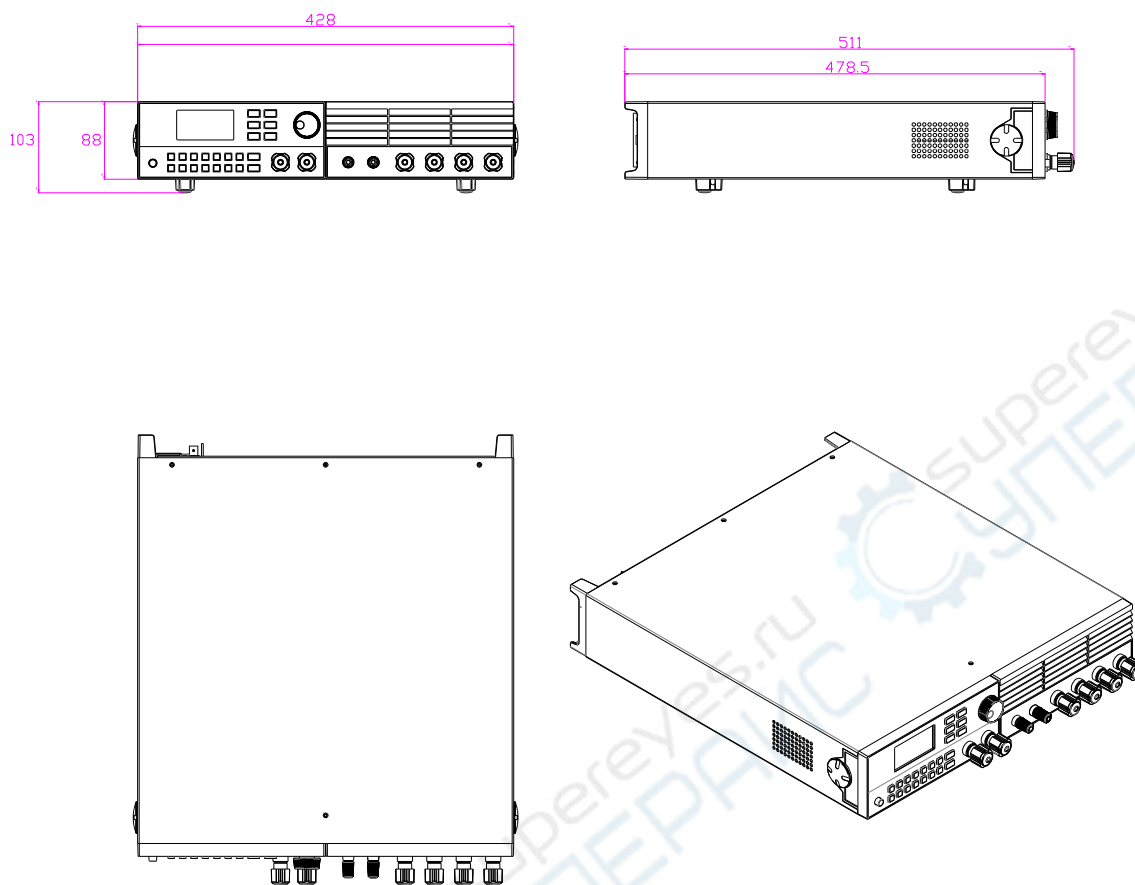
| Model                  |                        | JT6321A         |        | JT6322A         |        |
|------------------------|------------------------|-----------------|--------|-----------------|--------|
| Input Rating           | Power                  | 600W            |        | 1200W           |        |
|                        | Voltage                | 0~15V           | 0~150V | 0~15V           | 0~150V |
|                        | Current                | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Min. operating voltage | 1.4V@120A       |        | 1.4V@240A       |        |
| CC Mode                | Range                  | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Resolution             | 0.2mA           | 2mA    | 0.5mA           | 5mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| CV Mode                | Range                  | 0~15V           | 0~150V | 0~15V           | 0~150V |
|                        | Resolution             | 0.2mV           | 2mV    | 0.2mV           | 2mV    |
|                        | Accuracy               | 0.03%+0.03%FS   |        |                 |        |
| CP Mode                | Range                  | 600W            |        | 1200W           |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | 0.1%+0.1%FS     |        |                 |        |
| CR Mode                | Range                  | 0.012Ω~50KΩ     |        | 0.006Ω~25KΩ     |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | (0.1+0.04R)%    |        | (0.1+0.08R)%    |        |
| LED Mode               | Bandwidth              | 100kHz 以上       |        |                 |        |
|                        | Rd Coefficient         | 0.001~1         |        |                 |        |
| Dynamic Operation Mode | Range                  | 10uS~50S        |        |                 |        |
|                        | Resolution             | 2uS             |        |                 |        |
|                        | Accuracy               | 1uS+20PPM       |        |                 |        |
|                        | Slew rate              | 2.4A/mS~4.8A/uS |        | 4.8A/mS~9.6A/uS |        |
| Voltage Meas.          | Range                  | 0~15V           | 0~150V | 0~15V           | 0~150V |
|                        | Resolution             | 0.1mV           | 1mV    | 0.1mV           | 1mV    |
|                        | Accuracy               | 0.02%+0.03%FS   |        |                 |        |
| Current Meas.          | Range                  | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Resolution             | 0.1mA           | 1mA    | 0.1mA           | 1mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| Ripple Meas.           | Range                  | 0~15V           | 0~150V | 0~15V           | 0~150V |
|                        | Bandwidth              | 10Hz~100kHz     |        |                 |        |
|                        | Resolution             | 1mV             | 10mV   | 1mV             | 10mV   |

| Model                  |                        | JT6323A         |        | JT6324A         |        |
|------------------------|------------------------|-----------------|--------|-----------------|--------|
| Input Rating           | Power                  | 600W            |        | 1200W           |        |
|                        | Voltage                | 0~50V           | 0~500V | 0~50V           | 0~500V |
|                        | Current                | 0~6A            | 0~60A  | 0~12A           | 0~120A |
|                        | Min. operating voltage | 2.8V@60A        |        | 2.8V@120A       |        |
| CC Mode                | Range                  | 0~6A            | 0~60A  | 0~12A           | 0~120A |
|                        | Resolution             | 0.1mA           | 1mA    | 0.2mA           | 2mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| CV Mode                | Range                  | 0~50V           | 0~500V | 0~50V           | 0~500V |
|                        | Resolution             | 0.5mV           | 5mV    | 0.5mV           | 5mV    |
|                        | Accuracy               | 0.03%+0.03%FS   |        |                 |        |
| CP Mode                | Range                  | 600W            |        | 1200W           |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | 0.1%+0.1%FS     |        |                 |        |
| CR Mode                | Range                  | 0.047Ω~50KΩ     |        | 0.024Ω~25KΩ     |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | (0.1+0.02R)%    |        | (0.1+0.04R)%    |        |
| LED Mode               | Bandwidth              | 100kHz 以上       |        |                 |        |
|                        | Rd Coefficient         | 0.001~1         |        |                 |        |
| Dynamic Operation Mode | Range                  | 10uS~50S        |        |                 |        |
|                        | Resolution             | 2uS             |        |                 |        |
|                        | Accuracy               | 1uS+20PPM       |        |                 |        |
|                        | Slew rate              | 1.2A/mS~2.4A/uS |        | 2.4A/mS~4.8A/uS |        |
| Voltage Meas.          | Range                  | 0~50V           | 0~500V | 0~50V           | 0~500V |
|                        | Resolution             | 0.1mV           | 1mV    | 0.1mV           | 1mV    |
|                        | Accuracy               | 0.02%+0.03%FS   |        |                 |        |
| Current Meas.          | Range                  | 0~6A            | 0~60A  | 0~12A           | 0~120A |
|                        | Resolution             | 0.01mA          | 0.1mA  | 0.1mA           | 1mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| Ripple Meas.           | Range                  | 0~50V           | 0~500V | 0~50V           | 0~500V |
|                        | Bandwidth              | 10Hz~100kHz     |        |                 |        |
|                        | Resolution             | 1mV             | 10mV   | 1mV             | 10mV   |

| Model                  |                        | JT6325A         |        | JT6326A         |        |
|------------------------|------------------------|-----------------|--------|-----------------|--------|
| Input Rating           | Power                  | 1500W           |        | 1500W           |        |
|                        | Voltage                | 0~50V           | 0~500V | 0~15V           | 0~150V |
|                        | Current                | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Min. operating voltage | 2.8V@120A       |        | 1.4V@240A       |        |
| CC Mode                | Range                  | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Resolution             | 0.2mA           | 2mA    | 0.5mA           | 5mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| CV Mode                | Range                  | 0~50V           | 0~500V | 0~15V           | 0~150V |
|                        | Resolution             | 0.5mV           | 5mV    | 0.2mV           | 2mV    |
|                        | Accuracy               | 0.03%+0.03%FS   |        |                 |        |
| CP Mode                | Range                  | 1500W           |        | 1500W           |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | 0.1%+0.1%FS     |        |                 |        |
| CR Mode                | Range                  | 0.024Ω~50KΩ     |        | 0.006Ω~25KΩ     |        |
|                        | Resolution             | 16Bits          |        |                 |        |
|                        | Accuracy               | (0.1+0.04R)%    |        | (0.1+0.08R)%    |        |
| LED Mode               | Bandwidth              | 100kHz 以上       |        |                 |        |
|                        | Rd Coefficient         | 0.001~1         |        |                 |        |
| Dynamic Operation Mode | Range                  | 10uS~50S        |        |                 |        |
|                        | Resolution             | 2uS             |        |                 |        |
|                        | Accuracy               | 1uS+20PPM       |        |                 |        |
|                        | Slew rate              | 1.2A/mS~2.4A/uS |        | 2.4A/mS~4.8A/uS |        |
| Voltage Meas.          | Range                  | 0~50V           | 0~500V | 0~15V           | 0~150V |
|                        | Resolution             | 0.1mV           | 1mV    | 0.1mV           | 1mV    |
|                        | Accuracy               | 0.02%+0.03%FS   |        |                 |        |
| Current Meas.          | Range                  | 0~12A           | 0~120A | 0~24A           | 0~240A |
|                        | Resolution             | 0.2mA           | 2mA    | 0.1mA           | 1mA    |
|                        | Accuracy               | 0.03%+0.05%FS   |        |                 |        |
| Ripple Meas.           | Range                  | 0~50V           | 0~500V | 0~15V           | 0~150V |
|                        | Bandwidth              | 10Hz~100kHz     |        |                 |        |
|                        | Resolution             | 1mV             | 10mV   | 1mV             | 10mV   |



## 2.2. Installation Dimension



## 2.3. Additional Characteristics

AC power input range (which can be selected by selector switch at the back panel ):

(1) AC220V  $\pm 10\%$  50Hz/60Hz      (2) AC110V  $\pm 10\%$  50Hz/60Hz

Heat release method: Forced air cooling

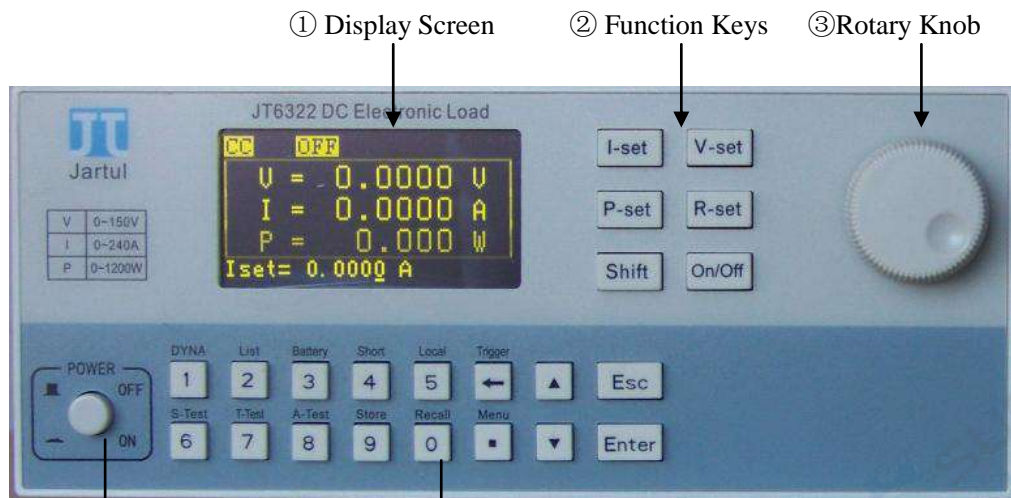
Working temperature: 0~40°C

Storage temperature: -20~70°C

Environment: For indoor use with maximum humidity 95%.

# Chapter Three: Quick Start

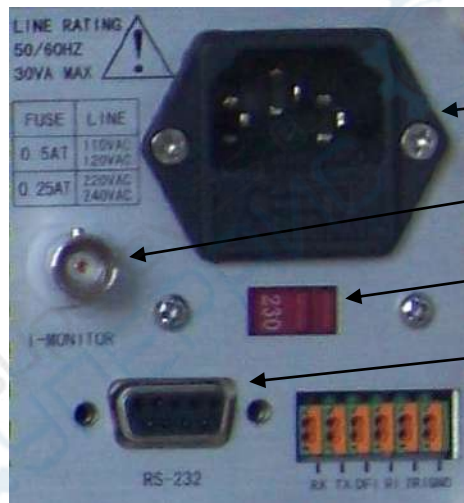
## 3.1. Front & Back Panel Overview



① Display Screen      ② Function Keys      ③ Rotary Knob  
 ④ Power Switch      ⑤ Numeric Keys      ⑥ Input Terminal



① Remote Sense Terminals      ② Input Terminal



① AC Socket (contains fuse)  
 ② Current Monitoring Terminal  
 ③ 220V/110V voltage selection  
 ④ RS232 interface  
 ⑤ Trigger/Parallel Operation Interfaces

## 3.2. Preparation Work before Power-on

- 1) The electronic load is available of 110V & 220V two kinds of working voltages. Please check if the working voltage of the electronic load matches the power voltage.
- 2) The fuse of the electronic load should match with the set voltage. Please check if the fuse is correctly installed according to the following table.

| AC input voltage setting | AC110V     | AC220V      |
|--------------------------|------------|-------------|
| Fuse Specification       | T2.5A/250V | T1.25A/250V |

### 3.3. Power-on Self Test

When the electronic load is powered on, it will show the manufacturer, model and software version, etc. Meanwhile, the electronic load will start system self-test. If self-test is not passed, please solve it according to the following table.

| Error Information                 | Solving Methods   |
|-----------------------------------|---|
| ROM Checksum Error                | Firmware code calibration error. Contact product manufacturer or distributor.       |
| SN Error                          | Serial number error. Contact product manufacturer or distributor.                   |
| Cal. Data Error                   | Calibration data error. Recalibrate or contact product manufacturer or distributor. |
| Temp. Data Error                  | Temperature data error. Contact product manufacturer or distributor.                |
| ADC / DAC Error                   | Hardware failure. Contact product manufacturer or distributor.                      |
| No Display & Intermittent buzzing | Please check if AC input voltage is too low.  |

### 3.4. Characters Showed at Status Bar

|       |  |       |   |
|-------|--|-------|---|
| ON    | Input opens.   | OFF   | Input closes.   |
| CC    | Electronic load is set as CC mode.                   | CV    | Electronic load is set as CV mode.                          |
| CP    | Electronic load is set as CP mode.                   | CR    | Electronic load is set as CR mode.                          |
| DYNA  | Electronic load is set as dynamic operation mode.    | List  | Electronic load is set as programmable list operation mode. |
| LED   | Electronic load is in LED mode.                      | Auto  | Electronic load is in automatic test mode.                  |
| RI    | Electronic load is in remote disable state.          | Trig  | Electronic load is waiting for a trigger signal             |
| Shift | Initiate double function keys.                       | Sense | The remote sensing is initiated.                            |
| Rmt   | Electronic load is in remote control mode.           | Lock  | Keyboard is locked and requires the password to unlock.     |
| OC    | Electronic load is in over current protection state. | OP    | Electronic load is in over power protection mode.           |

### 3.5. Characters Showed at Setting Bar

|      |                        |      |                           |
|------|------------------------|------|---------------------------|
| Iset | Set current in CC mode | Vset | Set voltage in CV mode    |
| Pset | Set power in CP mode   | Rset | Set resistance in CR mode |

### 3.6. Characters Showed at Measured Value Bar

|     |  |     |  |
|-----|--|-----|--|
| V   | Measured value of the input voltage            | I   | Measured value of the loading current            |
| P   | Measured value of the Loading average power    | R   | Measured value of the equivalent resistance      |
| Vpp | Peak to peak value of the input ripple voltage | Ipp | Peak to peak value of the loading ripple current |
| Vp+ | Peak value of the input voltage                | Vp- | Valley value of the input voltage                |
| Ip+ | Peak value of the loading current              | Ip- | Valley value of the loading current              |

|    |                                       |    |   |
|----|---------------------------------------|----|---|
| V  | Voltage unit-Volt                     | A  | Current unit-Ampere                     |
| W  | Power unit-Watt                       | R  | Resistance unit-Ohm                     |
| V+ | Peak voltage value unit-Volt          | V- | Valley voltage value unit-Volt          |
| A+ | Peak current value unit-Ampere        | A- | Valley current value unit-Ampere        |
| Vp | Peak to peak ripple voltage unit-Volt | Ap | Peak to peak ripple current unit-Ampere |

### 3.7. Keys

#### Common Keys

|       |  |        |                              |
|-------|--|--------|------------------------------|
| I-Set | Start or set CC mode                   | V-Set  | Start or set CV mode         |
| P-Set | Start or set CP mode                   | R-Set  | Start or set CR mode         |
| Shift | Enable or disable double function keys | On/Off | Input turns on or turns off. |
| 0~9   | Numeric keys                           | .      | Decimal point key            |
| ←     | Backspace key                          | Esc    | Escape key                   |
| ▲     | Arrow key                              | ▼      | Arrow key                    |
| Enter | Confirmation key                       |        |                              |

#### Double Function Keys

(Double function keys can be effective only when *Shift* key is pressed. And the screen will show the word *Shift* at the right corner of the screen.

|         |                                       |         |  |
|---------|---------------------------------------|---------|--|
| DYNA    | Start or set dynamic mode             | List    | Start or set List mode                   |
| Battery | Start or set battery test mode        | Short   | Enable or disable short-circuit function |
| Local   | Operate by front panel                | Trigger | Trigger operation                        |
| S-Test  | Static intelligent test mode          | T-Test  | Dynamic intelligent test mode            |
| A-Test  | Automatic test mode                   | Store   | Data storage                             |
| Recall  | Data recall                           | Menu    | Main menu                                |
| ▲       | Shortcut of Changing display formats. | ▼       | Shortcut of changing data measuring rate |

### 3.8. Ports at the rear panel

The electronic load has six 10MHZ isolated ports which are used for the input and output of trigger signals, and the synchronous control of multiple electronic loads.

| Port | Single load mode            | Master mode                                | Slave mode                                 | Property         |
|------|-----------------------------|--|--|------------------|
| GND  | Ground isolation            | Ground isolation                           | Ground isolation                           | Ground isolation |
| TRIG | Trigger signal input        | Trigger signal input                       | Reserved                                   | Input            |
| RI   | Disable remote signal input | Synchronous input of slave loads' signals  | Synchronous input of master load' signals  | Input            |
| DFI  | Device failure indication   | Synchronous output of master load' signals | Synchronous output of slave loads' signals | Output           |
| TX   | Trigger signal output       | UART data output                           | UART data output                           | Output           |
| RX   | Reserved                    | UART data input                            | UART data input                            | Input            |

#### Limit Parameters (Operating beyond this limit value may damage equipment interface)

| Parameters       | Description                         | Limit Value | Unit |
|------------------|-------------------------------------|-------------|------|
| V <sub>CEO</sub> | Pull-up voltage output from OC gate | -0.5 ~ 50   | V    |
| I <sub>CEO</sub> | Sink current output from OC gate    | 0~100       | mA   |

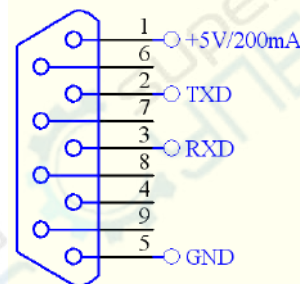
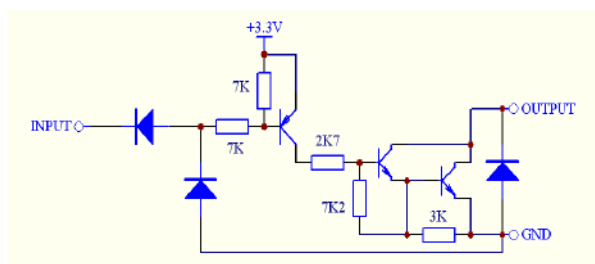
|                |               |         |   |
|----------------|---------------|---------|---|
| V <sub>I</sub> | Input voltage | -0.5~12 | V |
|----------------|---------------|---------|---|

### Working Condition

| Parameters      | Description       | Min | Type | Max | Unit |
|-----------------|-------------------|-----|------|-----|------|
| V <sub>IH</sub> | “H” Input voltage | 2.7 | 3.3  | 12  | V    |
| V <sub>IL</sub> | “L” Input voltage | 0   | 0    | 1   | V    |

Note: input open equaling “H”, short circuit in input and GND equaling “L”

The following left diagram is the electrical principle diagram of input port and output port. The electronic load also has a standard isolated RS232 port and a 5V/200mA isolated power supply output port. Please refer to the following right diagram for its wiring method. The electronic load also has a current monitoring terminal (I-MONITOR) for monitoring the loading waveform, which output range is 0-10V with 50Khz band width.



### 3.9. Menu Operation

| Menu                 |                           | Description   |
|----------------------|---------------------------|---|
| <b>Menu</b>          |                           | Main menu   |
| ┌<br>└               | <b>Config</b>             | Configuration   |
|                      | <b>Measure Rate</b>       | Setting Measuring rate. (Shortcut: Shift+ ▼)  |
|                      | Fast                      | Data update frequency: 10Hz   |
|                      | Medium                    | Data update frequency: 5Hz  |
|                      | Slow                      | Data update frequency: 2Hz  |
|                      | <b>Remote Sense</b>       | Setting remote sense  |
|                      | ON                        | Enable remote sense   |
|                      | OFF                       | Disable remote sense  |
|                      | <b>Input Recall</b>       | Recalling the load state  |
|                      | ON                        | Setting the load to its power-off state   |
|                      | OFF                       | Setting the load to its power-on state  |
|                      | <b>Key Sound</b>          | Setting the key sound   |
|                      | ON                        | The buzzer will sound when any key was pressed.   |
|                      | OFF                       | the buzzer will not sound when any key was pressed  |
|                      | <b>Key Lock</b>           | Setting the key lock  |
|                      | ON                        | Enable the key lock. Keys will be automatically locked when entering the code and then pausing for 5 seconds. |
|                      | OFF                       | Disable the key lock  |
|                      | <b>Knob Lock</b>          | Setting the rotary knob fine tuning function  |
|                      | ON                        | Enable the rotary knob fine tuning function   |
|                      | OFF                       | Disable the rotary knob fine tuning function  |
| <b>Shortcut Call</b> | Setting the shortcut call |   |



|                         |                |   |
|-------------------------|----------------|---|
|                         | ON             | Enable the shortcut call  |
|                         | OFF            | Disable the shortcut call   |
| <b>Trig.In Ctrl.</b>    |                | Setting the function of the trigger input terminals   |
|                         | ON             | The trigger input terminals are used to control the load input  |
|                         | OFF            | The trigger input terminals are used for timing measurement   |
| <b>Trig.In Speed</b>    |                | Setting the trigger signals response speed  |
|                         | High           | Quick response, fit for high quality signals (e.g. program-controlled signals )   |
|                         | Low            | Slow response, fit for low quality signals (e.g. foot switch )  |
| <b>Sync. Mode</b>       |                | Setting synchronous control modes   |
| Sync. Mode              | Sync. Run      |   |
|                         | ON             | Enable synchronous control  |
|                         | OFF            | Disable synchronous control   |
|                         | Parallel       |   |
|                         | ON             | Enable parallel control and intelligent power allocation  |
|                         | OFF            | Disable parallel control and intelligent power allocation   |
|                         | Role           |   |
|                         | Master         | Setting the load as the master load   |
|                         | Slave          | Setting the load as the slave load  |
|                         | Slave ID       |   |
| Scan Slave              |                | Slave load scanning operation. This is used for adjustment when loads are in parallel control. Only the master load has the function. |
| <b>Communication</b>    |                | Setting communication parameters  |
|                         | Baud Rate      | Setting Baud Rate (2400~115200)   |
|                         | Comm Parity    | Setting Comm. Parity. (none/even/odd)   |
|                         | Multi-Point    | Setting the multi-point communication   |
|                         | ON             | Enable the multi-point communication  |
|                         | OFF            | Disable the multi-point communication   |
|                         | Address Set    | Setting the load address when in multi-point communication  |
| <b>Display</b>          |                | Setting personalized display  |
|                         | Format         |   |
|                         | 2 items        | Displaying 2 items (Characters displayed are big)   |
|                         | 3 items        | Displaying 3 items (Characters displayed are medium)  |
|                         | 6 items        | Displaying 6 items (Characters displayed are small)   |
|                         | Brightness     |   |
| <b>Default Settings</b> |                | Restoring to factory-default settings   |
|                         | Yes            | Confirming to restore to factory-default settings   |
| <b>Device Info</b>      |                | Displaying the device information   |
| <b>System Set</b>       |                | Setting the system  |
| System Set              | <b>V Range</b> |   |
|                         | High           | Setting the voltage as high voltage range   |
|                         | Low            | Setting the voltage as low voltage range  |
|                         | <b>I Range</b> |   |

|                           |                    |             |  |                                 |
|---------------------------|--------------------|-------------|--|---------------------------------|
|                           |                    | High        | Setting the current as high current range                |                                 |
|                           |                    | Low         | Setting the current as low current range                 |                                 |
|                           | <b>I_prot</b>      |             | Setting current protection                               |                                 |
|                           | <b>P_prot</b>      |             | Setting power protection                                 |                                 |
|                           | <b>Von</b>         |             | Setting Von value  |                                 |
|                           | <b>Voff</b>        |             | Setting Voff value                                       |                                 |
|                           | <b>↗ Rate</b>      |             | Setting current rising slew rate                         |                                 |
|                           | <b>↘ Rate</b>      |             | Setting current falling slew rate                        |                                 |
|                           | <b>Source</b>      |             | Setting sources of the devices tested                    |                                 |
|                           |                    | CV Source   | Setting the device tested as CV source                   |                                 |
|                           |                    | CC Source   | Setting the device tested as CC source                   |                                 |
|                           |                    | Auto Detect | Detecting automatically the devices tested               |                                 |
| <b>Dynamic Load</b>       |                    |             | Dynamic mode   |                                 |
| <b>DYNA</b>               | <b>Dynamic Set</b> |             | Setting dynamic mode parameters                          |                                 |
|                           |                    | Ia          | Setting low level current                                |                                 |
|                           |                    | Ta          | Setting dwelling time of low level current               |                                 |
|                           |                    | Ib          | Setting high level current                               |                                 |
|                           |                    | Tb          | Setting dwelling time of high level current              |                                 |
|                           |                    | ↗ Rate      | Setting current rising slew rate                         |                                 |
|                           |                    | ↘ Rate      | Setting current falling slew rate                        |                                 |
|                           |                    | Mode        |  | Selecting DYNA working modes    |
|                           |                    | Mode        | Continuous   | Setting load as continuous mode |
|                           |                    |             | Pulse  | Setting load as pulse mode      |
|                           | Toggle             |             | Setting load as toggle mode                              |                                 |
| <b>Enter Dynamic Mode</b> |                    |             | Starting Dynamic mode                                    |                                 |
| <b>LED Mode</b>           |                    |             | Setting LED mode   |                                 |
|                           | LED Mode Set       |             | Setting LED mode parameters                              |                                 |
|                           |                    | LED Vo      | Setting the rated output voltage of the LED power supply |                                 |
|                           |                    | LED Io      | Setting the rated output current of the LED power supply |                                 |
|                           |                    | Rd Coeff    | Setting the Rd coefficient                               |                                 |
| Enter LED Mode            |                    |             | Entering LED mode  |                                 |
| <b>List</b>               |                    |             | Setting the List   |                                 |
|                           | File               |             | Selecting List files (1~8)                               |                                 |
|                           | Load File          |             | Starting List operation mode                             |                                 |
|                           | Edit File          |             | Editing List files                                       |                                 |
|                           |                    | New Step    | Adding a new step to the List file                       |                                 |
|                           |                    | Step n      | Editing n step(1-200) parameters                         |                                 |
|                           |                    | Current     | Editing n step loading current                           |                                 |
|                           |                    | SR          | Editing n step current rising slew rate                  |                                 |
|                           |                    | Dwell       | Editing n step current dwelling time                     |                                 |
|                           |                    | Delete      | Deleting the step  |                                 |
| Clear File                |                    |             | Clearing the present List files                          |                                 |
| Setup                     |                    |             | Selecting the List working mode                          |                                 |
|                           | Mode               |             | Setting the List working mode                            |                                 |
|                           |                    | Continuous  | Continuous mode  |                                 |

|                       |                    |                                    |  |  |  |
|-----------------------|--------------------|------------------------------------|--|--|--|
|                       |                    | Count                              | Count mode (1~9999999)   |  |  |
|                       |                    | Step                               | Single step mode   |  |  |
|                       |                    | Count                              | Setting the repeating times of the count mode. This is only effective to the count mode. |  |  |
| <b>Battery</b>        |                    |                                    | Testing the battery capacity   |  |  |
| Battery               | Discharge Set      |                                    | Setting the battery discharge parameters   |  |  |
|                       |                    | Mode                               | Setting the battery discharge working mode CC/CP/CR                                      |  |  |
|                       |                    | Value                              | Setting the battery loading value at discharge state                                     |  |  |
|                       |                    | Stop Condition                     |  | Setting the battery stopping discharge condition |  |
|                       |                    |                                    | Enable   | Enable the battery stopping discharge condition  |  |
|                       |                    |                                    | Voltage  | Voltage  | Enable the battery stopping discharge voltage  |
|                       |                    |                                    |  | Capacity   | Enable the battery stopping discharge capacity |
|                       |                    |                                    |  | Time   | Enable the battery stopping discharge time     |
|                       |                    | Voltage                            |  | Battery stopping discharge voltage               |  |
|                       | Capacity           |                                    | Battery stopping discharge capacity  |  |  |
|                       | Time               |                                    | Battery stopping discharge time  |  |  |
| Start Test            |                    |                                    | Starting battery capacity test   |  |  |
| <b>Static Test</b>    |                    |                                    | Setting the static test  |  |  |
| S-Test                | <b>OCP Test</b>    |                                    | Setting the OCP test   |  |  |
|                       | OCP Test           | OCP Set                            |  | Setting the OCP test parameters                  |  |
|                       |                    | OCP Set                            | I start  | Setting the starting current value               |  |
|                       |                    |                                    | I end  | Setting the ending current value                 |  |
|                       |                    |                                    | Steps  | Setting the No. of current increasing steps      |  |
|                       |                    |                                    | Dwell  | Setting the dwelling time of each step           |  |
|                       | V trig             |                                    | Setting the trigger level of the OCP test  |  |  |
|                       | Start Test         |                                    |  | Starting OCP test mode                           |  |
|                       | <b>Load Effect</b> |                                    |  | Setting load effect                              |  |
|                       | Load Effect        | Load Set                           |  | Setting load effect loading parameters           |  |
|                       |                    | Load Set                           | Imin   | Setting the low-level loading current            |  |
|                       |                    |                                    | Imax   | Setting the high-level loading current           |  |
|                       |                    |                                    | Inormal  | Setting the normal working current               |  |
|                       |                    |                                    | Delay  | Setting the delay time of the loading current    |  |
|                       | Start Test         |                                    |  | Starting load effect test                        |  |
|                       | <b>Volt. Trig.</b> |                                    |  | Voltage level trigger initiate the static test   |  |
|                       |                    | Volt. Trig                         |  | Enable or disable voltage level trigger          |  |
|                       |                    | OFF                                | Disable the voltage level trigger  |  |  |
|                       |                    | ON                                 | Enable the voltage level trigger   |  |  |
| Vtrig                 |                    | Setting the trigger voltage        |  |  |  |
| <b>Transient Test</b> |                    |                                    | Setting transient test   |  |  |
| T-Test                | <b>Sweep</b>       |                                    | Setting frequency sweep  |  |  |
|                       | Sweep              | Sweep Set                          |  | Setting frequency sweep parameters               |  |
|                       |                    | Imin                               | Setting low-level current  |  |  |
|                       |                    |                                    | Setting high-level current   |  |  |
|                       |                    | Fstart                             |  | Setting the sweep starting frequency             |  |
| Fend                  |                    | Setting the sweep ending frequency |  |  |  |



|           |  |   |  |   |
|-----------|--|---|--|---|
|           |  | Fstep   | Setting the step frequency   |   |
|           |  | Dwell   | Setting the dwelling time of one frequency                               |   |
|           |  | Duty  | Setting the duty cycle   |   |
|           |  | ↗ Rate  | Setting the current rising slew rate                                     |   |
|           |  | ↘ Rate  | Setting the current falling slew rate                                    |   |
|           |  | Start Test  | Starting Sweep test mode   |   |
|           |  | Sweep Mode  | Setting Sweep working modes  |   |
|           |  | Auto  | Automatic mode   |   |
|           |  | Manual  | Manual mode. Users can use rotary knob to fine tune the sweep frequency. |   |
|           |  | <b>Timing</b>                                     | Setting timing measurement   |   |
| Timing    |  | Load Set  | Setting the loading condition  |   |
|           |  | Mode  | Setting the loading mode   |   |
|           |  | Value   | Setting the loading value  |   |
|           |  | Trig.Start  | Setting the trigger starting condition                                   |   |
|           |  | Trig.Start  | Signal   | Setting the trigger signal source                   |
|           |  |   | Voltage  | Setting trigger signal source as inputting voltage. |
|           |  |   | Current  | Setting trigger signal source as loading current.   |
|           |  |   | Ext.TRIG   | Setting trigger signal source as external trigger.  |
|           |  | Edge  | Setting the trigger edge   |   |
|           |  | Rise  | Being effective by rising edge trigger                                   |   |
|           |  | Fall  | Being effective by falling edge trigger                                  |   |
|           |  | Level   | Setting trigger voltage level  |   |
|           |  | Trig.End  | Setting the trigger ending condition                                     |   |
|           |  | Signal  | Setting the trigger signal source  |   |
|           |  | Edge  | Setting the trigger edge   |   |
|           |  | Level   | Setting the trigger voltage level  |   |
|           |  | Start Test  | Starting the timing measurement mode                                     |   |
|           |  | <b>OVP Test</b>                                   | Setting OVP test   |   |
|           | Vtrig  | Setting the trigger voltage level of the OVP test |  |   |
|           | Start Test                                   | Starting the OVP test mode                        |  |   |
|           |  | <b>Auto Test</b>                                  |  |   |
| A-Test    |  | File  | Selecting automatic test files (1~8)                                     |   |
|           |  | Load File   | Starting automatic test mode   |   |
|           |  | Edit File   | Editing the file   |   |
|           | Edit File                                    |   | New Step   | Adding a new step to the A-test file                |
|           |  |   | Step n   | Editing the n step parameters in A-test file        |
|           |  | Step n  | Load   | Setting the loading mode                            |
|           |  |   | Load Mode  | Setting the loading mode                            |
|           |  |   | Value  | Setting the loading parameters.                     |
|           |  | SPEC  | Setting the specification type   |   |
|           |  | SPEC Type   | Setting the specification type. This is related to the loading mode.     |   |
|           | Max Limit                                    | Setting the maximum limit of being qualified      |  |   |
| Min Limit | Setting the minimum limit of being qualified |   |  |   |

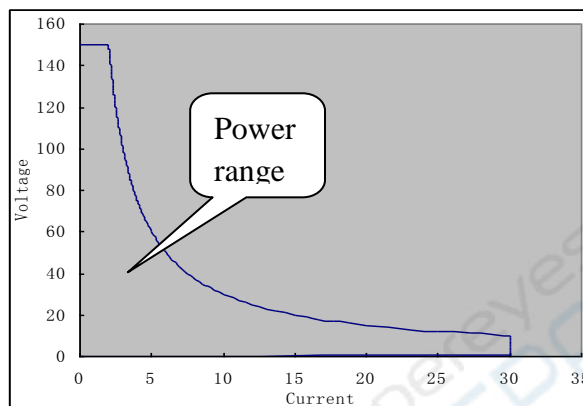
|       |                |                                  |  |
|-------|----------------|----------------------------------|--|
|       |                | Delay                            | Setting the delay time   |
|       | Clear File     |                                  | Clearing the present A-test file   |
|       | Setup          |                                  | Automatic test setup   |
| Setup | Fail Op.       |                                  | Setting the handling method when a step value is tested as unqualified   |
|       |                | Continue                         | Continuing to finish the A-test when a step value is tested as unqualified   |
|       |                | Abort                            | Stopping the A-test immediately when a step value is tested as unqualified   |
|       | Trigger Output |                                  | Setting the trigger output   |
|       |                | Condition                        |  |
|       |                | Pass                             | Initiating trigger output (TX terminal ) when passing the test   |
|       |                | Fail                             | Initiating trigger output (TX terminal ) when failing the test   |
|       |                | End                              | Initiating trigger output (TX terminal ) when finishing the test   |
|       |                | Disable                          | Disable the trigger output   |
|       |                | Output Mode                      |  |
|       |                | Level                            | Voltage level trigger (being effective only with low voltage level)  |
|       |                | Pulse                            | Pulse trigger ( when passing the test, output pulse width is 4.2ms; when failing the test, output pulse width is 8.4ms ) |
|       | Auto Run       |                                  | Setting the automatic run parameters   |
|       |                | Volt. Trig                       |  |
|       |                | OFF                              | Disable the voltage level trigger  |
|       | ON             | Enable the voltage level trigger |  |
|       | Vtrig          |                                  | Setting the trigger voltage level value  |

## Chapter Four: Panel Operation

### 4.1. System Set

#### 4.1.1. Electronic Load Operation Range

Electronic load works in the range of Rated Current, Rated Voltage and Rated Power. Please refer to the right diagram for JT6312A power range.



#### 4.1.2. Voltage & Current Range

Electronic load is available of 2 voltage ranges and current ranges. Once low voltage range and current range is selected, the corresponding measuring range will become one tenth of that of high level and the resolution will be 10 times higher. Besides, when in low current range, the maximum current slew rate can be set as one tenth of that of high level.

#### 4.1.3. Over Current Protection (OCP)

Electronic load possesses OCP function. This function can ensure the loading current will never exceed the current protection. The current protection can be any value no bigger than rated current.

#### 4.1.4. Over Power Protection (OPP)

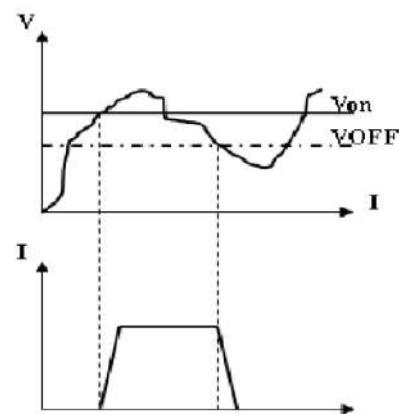
Electronic load possesses OPP function. This function can ensure the loading power will never exceed the power protection. The power protection can be any value no bigger than rated power.

#### 4.1.5. Current Slew Rate

Electronic load supports current rising and falling slew rate programmable. The current input range is related to rated input current. Please refer to the technical data in Section 2.1.

#### 4.1.6. Von/Voff

Electronic load supports Von/Voff function, the working principle of which is as the right diagram. When input voltage is higher than or equals Von voltage, the electronic load will start to sink current. When the input voltage is below or equals Voff value, the input state of the load will be off and the load will stop the current loading.



Von/Voff loading Current Waveform

#### 4.1.7. Types of Measured Sources

There are two types of measured source: CV source and CC source. Please select the right measured source. When in CR mode, the electronic load supports automatically detecting and matching the measured source, so users can set the measured source as “Auto Detect”.

### 4.2. Input Control

#### 4.2.1. Input On/Off

Electronic load input can be toggled on/off through the *On/Off* key on the front panel. When input is on, the word *ON* will be showed at the screen status bar. When input is off, the word *OFF* will be showed at the screen status bar.

#### 4.2.2. Short Circuit

Electronic load can simulate a short circuit at its input by setting the load with full-scale current. The short circuit can be set on or off by the double function key *Short* at the front panel. When short-circuit is on, the word *Short* will be showed at the screen status bar. When exiting from short circuit function, the electronic

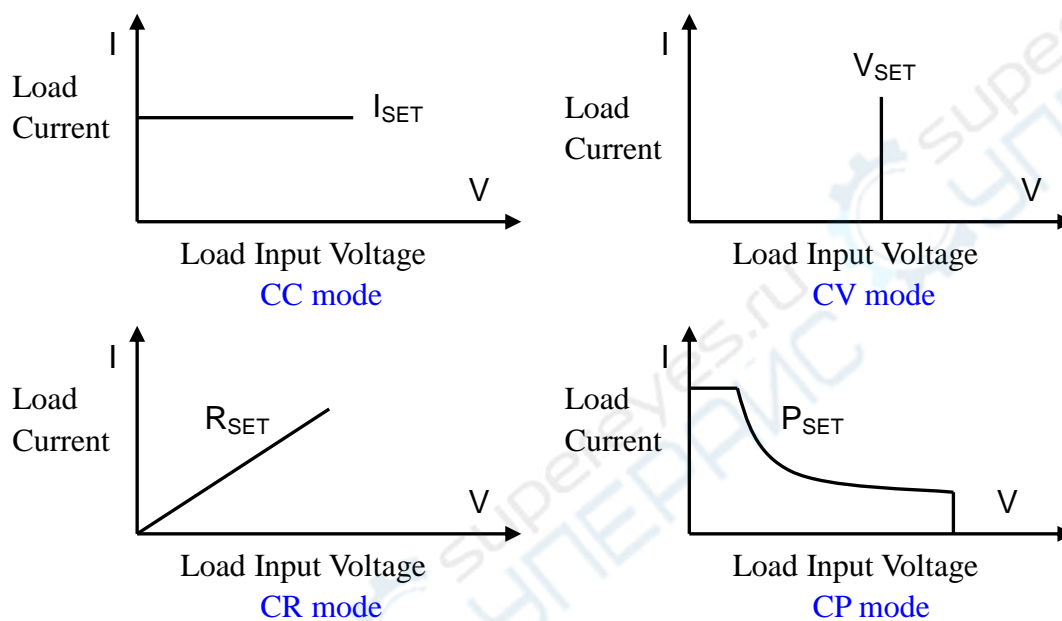
load will go back to its previous state before running short circuit function. Maximum short circuit current is the protection current set in load system.

### 4.3. Trigger Operation

In some special condition, the electronic load requires an external trigger signal so as to launch a program or allow synchronization with other test equipments. The electronic load supplies three trigger methods:

- Using the double function key **Trigger** at the front panel. Pressing the key **Trigger** once finishes one trigger.
- Using the TRIG port at the back panel. Lowing the TRIG port voltage level finishes one trigger.
- Using the software. Receiving one demand finishes one trigger.

### 4.4. Basic Operation Modes



#### 4.4.1. Constant Current Mode (CC)

In CC mode, the electronic load will sink a current in accordance with the programmed current value regardless of input voltage. The CC mode can be set by the following steps: first press the key **I-set** and then input the programmed current value, followed by pressing the key **Enter** for confirmation.

#### 4.4.2. Constant Voltage Mode (CV)

In CV mode, the electronic load will sink current to control the voltage of the source to the programmed voltage value. The CV mode can be set by the following steps: first press the key **V-set** and then input the programmed voltage value, followed by pressing the key **Enter** for confirmation.

#### 4.4.3. Constant Power Mode (CP)

In CP mode, the electronic load will sink a current according to the programmed power. The CP mode can be set by the following step: first press the key **P-set** and then input the programmed power value, followed by pressing the key **Enter** for confirmation.

The electronic load not only supports CP mode when measured source is CV source, but also supports CP mode when measured source is CC source. Users should select the source type from **System Menu**. If users select **Auto Detect**, this means CV Source is selected.

#### 4.4.4. Constant Resistance Mode (CR)

In CR mode, the load will sink a current linearly proportional to the input voltage in accordance with the programmed resistance. The CR mode can be set by the following step: first press the key **R-set** and then input the programmed resistance value, followed by pressing the key **Enter** for confirmation.

The electronic load not only supports CR mode when measured source is CV source, but also supports CR mode when measured source is CC source. Users should select the source type from *System Menu*. If users hope the system to automatically detect and match the measured source type, please set the source type as *Auto Detect*.

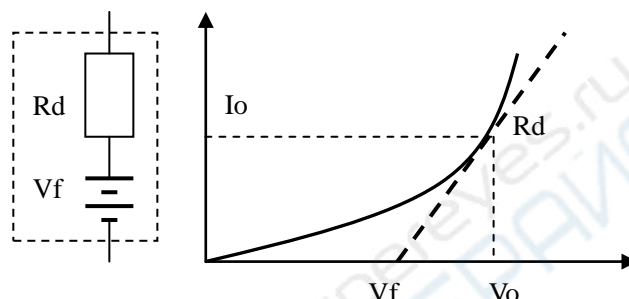
## 4.5. LED Mode

The electronic load has LED simulation function. The LED equivalent circuit diagram, as the right diagram showed, is to connect the resistance **Rd** with the voltage source **Vf** in series. Its VI curve is equivalent to tangent of the real LED nonlinear VI curve at the operating point ( $V_o$ ,  $I_o$ ).

In LED mode, three parameters  $V_o$ ,  $I_o$  & Rd Coeff need to be set.  $I_o$  is the rated output current of the measured LED power supply;  $V_o$  is the corresponding working voltage when LED power supply is at  $I_o$  working current.  $V_o$  can be known by the VI curve in the LED specifications book. The electronic load is usually used to test several LED in series, so  $V_o$  should be set as several times of that of the single LED or as any value within the output voltage range of the LED power supply. Rd Coeff is the ratio of the equivalent series resistance (Rd) with the total equivalent resistance ( $V_o / I_o$ ) of the electronic load, that is,  $Rdcoeff = Rd / (V_o / I_o)$ . In series applications, Rdcoeff value is only related to the VI curve of the selected LED and has nothing to do with the number of LED in series.

Users can get the  $I_o$  according to the rated output current of the LED power supply and then count the Rdcoeff with the help the VI curve in the LED specification book. Then adjust the voltage to any value within the output voltage range of the LED power supply. In this way, the electronic load can real simulate LED loading.

Users can also the shortcut key **Shift+R-set** to enter LED mode. When setting those three parameters, users can also use the rotary knob to adjust  $V_o$ .

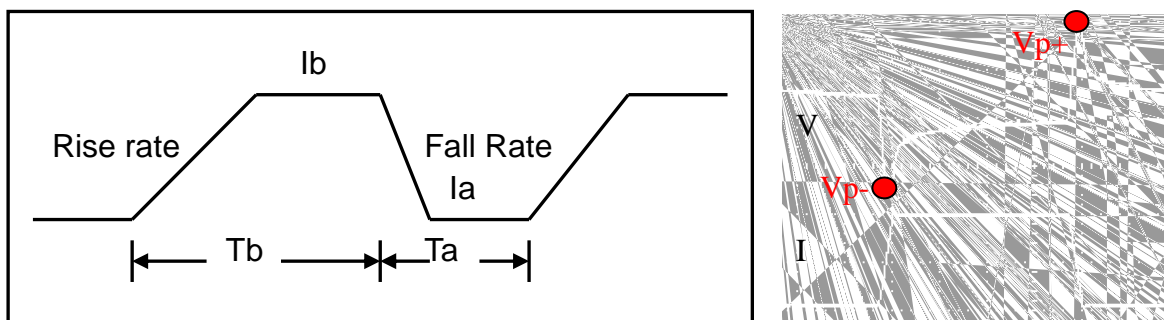


| Starting LED Mode: Menu: LED Mode: Enter LED Mode (Shortcut key: <b>Shift+R-set</b> ) |   |
|---|---|
| LED mode parameters setting path: Menu: LED Mode : LED Mode Set:                      |   |
| Parameters  | Description   |
| LED $V_o$   | The corresponding working voltage when LED power supply is at $I_o$ working current. Please refer to rated output voltage range of the LED power supply |
| LED $I_o$   | Working current, that is, the rated output current of the LED power supply.   |
| Rd Coeff  | Rd coefficient  |

## 4.6. Dynamic Operation (DYNA)

Dynamic operation enables the electronic load to periodically switch between two load currents, as might be required for testing the dynamic performance of power supplies. Its working principle is as the following diagram. The electronic load starts loading from current  $I_a$ , and after  $T_a$  dwelling time, the current  $I_a$  will rise to current  $I_b$  according to the programmed current rising slew rate. The rising time and the electronic load loading time with current  $I_b$  is called dwelling time  $T_b$ . After  $T_b$  dwelling time, the current  $I_b$  will fall to current  $I_a$  according to the programmed current falling slew rate. Then the electronic load will go on loading with current  $I_a$ . At the moment of current changing, the input voltage will either become voltage overshoot or voltage drop. And the electronic load will real-time display peak voltage ( $V_{p+}$ ) when in overshoot and valley voltage ( $V_{p-}$ ) when in drop.





| DYNA: Enter Dynamic Mode                                 |  |      |
|--|--|------|
| DYNA: Dynamic Set:                                       |  |      |
| Parameters   | Description  | Unit |
| Ia   | Low-level loading current  | A    |
| Ta   | Low-level current dwelling time (range:10uS~50S; resolution: 2uS)  | mS   |
| Ib   | High-level loading current   | A    |
| Tb   | High-level current dwelling time (range:10uS~50S; resolution: 2uS)   | mS   |
| ↗ Rate   | Current rising slew rate   | A/uS |
| ↘ Rate   | Current falling slew rate  | A/uS |
| Mode   | Working modes (Continuous/ Pulse/ Toggle)  | -    |
| DYNA working modes setting path DYNA: Dynamic Set: Mode: |  |      |
| Continuous   | In continuous mode, the electronic load will periodically switch between the low and high loading current according to the programmed current slew rate and dwelling time.   |      |
| Pulse  | In pulse mode, the electronic load current will rise to current <b>Ib</b> according to the programmed current rising slew rate when receiving a trigger signal. After <b>Tb</b> dwelling time, the current <b>Ib</b> will fall to the current <b>Ia</b> according to the programmed current falling slew rate. |      |
| Toggle   | In toggle mode, the electronic load current will rise to the current <b>Ib</b> according to the programmed current rising slew rate or fall to the current <b>Ia</b> according to the programmed current falling rate once receiving a trigger signal.   |      |

#### 4.7. List Operation (List)

List function lets you simulate a real electronic load or edit the electronic load loading waveforms. The electronic load will start loading according to the programmed list files. You can program up to 8 files in the list and each file is with 200 steps. The current slew rate of each step can be programmed.

| Selecting a list file: List: File: List m ( $1 \leq m \leq 8$ )                 |  |      |
|---|--|------|
| Clearing a list file: List: Clear File  |  |      |
| Adding a new step to a certain list file: List: Edit File: New Step             |  |      |
| Starting list file: List: Load File   |  |      |
| A step parameters setting path List: Edit File: Step n: ( $1 \leq n \leq 200$ ) |  |      |
| Parameters  | Description  | Unit |
| Current   | Loading current  | A    |
| Dwell   | Dwelling time (range: 10uS-50S, resolution: 2uS)                                 | mS   |
| SR  | Current slew rate.   | A/uS |
| List working mode setting path: List: Mode :                                    |  |      |
| Continuous  | In continuous mode, the electronic load starts loading continuously according to |      |

|       |  |
|-------|--|
|       | programmed steps sequence.   |
| Count | In count mode, once receiving a trigger signal, the electronic load starts loading according to the programmed steps sequence. After repeating for “Count” times, the electronic load will stop loading. Count setting range can be 1~9999999. |
| Step  | In step mode, once receiving a trigger signal, the electronic load starts loading according to that step setting parameters.   |

## 4.8. Measured Items

### 4.8.1. Average Voltage (V) & Average Current (I) Measurement

The electronic load supports average voltage (V) and average current (I) measurement and display them in real-time. The maximum measuring bandwidth of the load is 250KHZ. Even when the ripple is big, the load can also achieve the accurate measurement. Besides, the load also provides three measuring rates (Refer to the Section 4.18—Personalized Display Setting for the detail). The fastest measuring rate is 10Hz, which satisfy the fast measuring demands while the slowest measuring rate is 2Hz, the stability of which is better even under harsh conditions. The medium measuring rate is 5Hz. Both the voltage and the current can be set into high and low two ranges. When in low range, the load can achieve higher measuring accuracy.

### 4.8.2. Ripple Voltage ( $V_{PP}$ ) and Ripple Current ( $I_{PP}$ ) Measurement

The electronic load supports ripple voltage ( $V_{PP}$ ) and Ripple current ( $I_{PP}$ ) measurement and display them in real-time.

Different from the traditional method of using oscilloscopes add capacitance to measure the ripple, the load measuring ripple possesses good flatness (when in bandwidth range). Therefore, the load can measure the ripple more accurately with high reproducibility.

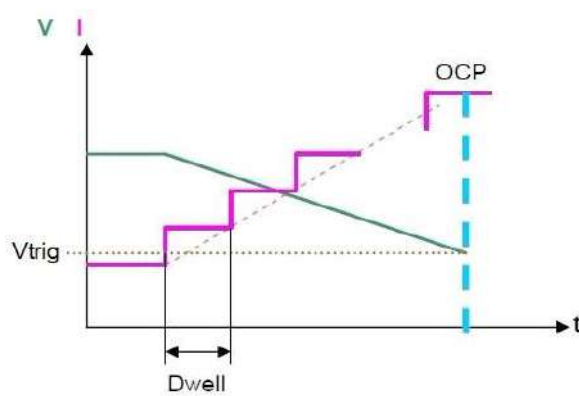
### 4.8.3. Peak Voltage ( $V_{P+}/V_{P-}$ ) and Peak Current ( $I_{P+}/I_{P-}$ ) Measurement

The electronic load supports peak voltage ( $V_{P+}/V_{P-}$ ) and peak current ( $I_{P+}/I_{P-}$ ) measurement and display them in real-time. In dynamic loading mode, this function shows more importance.  $V_{P+}$  means the voltage overshoot in transient test while  $V_{P-}$  means the voltage drop in transient test. The importance of this function lie in that in automatic test (A-test) (Refer to Section 4.11), the load can achieve the qualification judgment of the transient test.

## 4.9. Static Test Mode (S-Test)

### 4.9.1. Over Current Protection Test (OCP)

The electronic load has over current protection function, the principle of which is as the right diagram. The electronic load starts loading from starting current ( $I_{start}$ ) and gradually increase the current to the ending current ( $I_{end}$ ) according to the programmed steps. When detecting that the input voltage level has decreased to trigger voltage level ( $V_{trig}$ ), the electronic load will think the measured power supply has started OCP and the current at that time is the measured power supply’s OCP point. Meanwhile, the electronic load will fully monitor input power, automatically capture maximum power ( $P_{max}$ ) and the voltage (V) & current (I) at the maximum power.



Starting OCP test: S-Test: OCP Test: Start Test

OCP parameters setting path: S-Test: OCP Test: OCP Set:

| Parameters | Description                                | Unit |
|------------|--|------|
| I start    | Starting current                           | A    |
| I end      | Ending current                             | A    |
| Steps      | Total steps of current increasing (1~1000) | -    |
| Dwell      | Dwelling time of each step (0.01~999.99)   | mS   |
| V trig     | Trigger voltage level                      | V    |

#### 4.9.2 Load Effect Test (Load Effect)

The electronic load has load effect test function, the principle of which is as the following diagram. The electronic load starts loading at three different currents (Imin, Inormal, Imax). After programmed delay time, the electronic load will automatically record the corresponding voltages when loading at those three different currents and count the electronic load regulation,  $\Delta V$  and measured power supply resistance according to the following formula.

$$V_{max} = V_{dc}@I_{min}$$

$$V_{min} = V_{dc}@I_{max}$$

$$\Delta V = V_{max} - V_{min}$$

$$R_s = \Delta V / (I_{max} - I_{min})$$

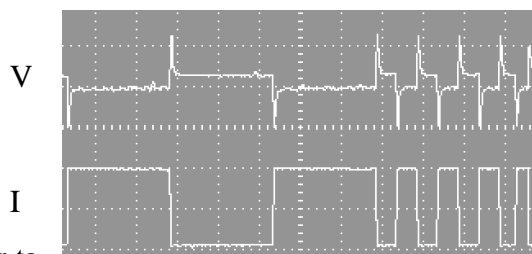
$$\text{Regulation} = \Delta V / V_{normal}$$

| Starting load effect test: S-Test: Load Effect: Start Test               |   |      |
|--|---|------|
| Load effect test parameters setting path: S-Test: Load Effect: Load Set: |   |      |
| Parameters   | Description                             | Unit |
| Imin   | Low-level loading current               | A    |
| Imax   | High-level loading current              | A    |
| Inormal  | Normal working current                  | A    |
| Delay  | Loading current delay time of each step | S    |

### 4.10 Transient Test (T-Test)

#### 4.10.1 Dynamic Frequency Sweep (Sweep)

The electronic load has dynamic frequency sweep function. With this function, the electronic load can capture the peak voltage value ( $V_{p+}$ ) and valley voltage value ( $V_{p-}$ ) of the measured power supply under the worst circumstances. The electronic load periodically switches between two load levels according to the programmed current rising slew rate and falling slew rate, which is similar to



the load in dynamic mode. The difference is that the dwelling time of each current level is determined by sweep frequency and duty cycle when in dynamic frequency sweep function. Meanwhile, the sweep frequency starts from starting frequency ( $F_{start}$ ) and rise to ending frequency ( $F_{end}$ ) step by step according to the programmed each step frequency ( $F_{step}$ ) and programmed each frequency dwelling time ( $D_{well}$ ). When the electronic load starts sweeping, at the moment of current changing, the input voltage will either become voltage overshoot or voltage drop. And electronic load will real-time display peak voltage ( $V_{p+}$ ) when in overshoot and valley voltage ( $V_{p-}$ ) when in drop. When sweeping is finished, the electronic load will display the maximum peak voltage, the minimum valley voltage, and the frequency point at which the maximum peak voltage and minimum valley voltage occurs.

| Starting sweep test: T-Test: Sweep: Start Test           |                           |      |
|--|---------------------------|------|
| Sweep parameters setting path: T-Test: Sweep: Sweep Set: |                           |      |
| Parameters   | Description               | Unit |
| Imin   | Low-level loading current | A    |



|   |   |      |
|---|---|------|
| Imax  | High-level loading current  | A    |
| Fstart  | Starting frequency, 0.01Hz~50Khz  | Hz   |
| Fend  | Ending frequency, 0.01Hz~50Khz  | Hz   |
| Fstep   | Step frequency, 0.01Hz~50Khz  | Hz   |
| Dwell   | Dwelling time of each frequency, 0.001S~99.999S   | s    |
| Duty  | Duty cycle, 1%~99%  | %    |
| ↗ Rate  | Current rising slew rate  | A/us |
| ↘ Rate  | Current falling slew rate   | A/us |
| Sweep mode setting path: T-Test: Sweep: Sweep Mode: |   |      |
| Auto  | Automatic mode  | -    |
| Manul   | Manual mode. Sweep frequency can be adjusted by rotary knob according to the programmed step frequency (Fstep). | -    |

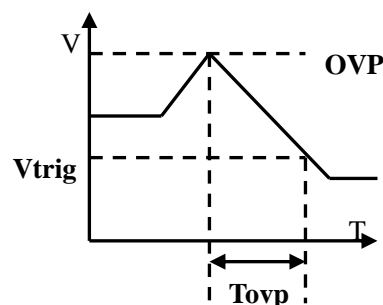
#### 4.10.2 Timing Measurement (Timing)

Electronic load has timing measurement function with 0.1mS accuracy. In programmed condition, the electronic load can automatically capture two trigger signals and count out the time interval of two signals occurring. When finishing test, the electronic load will automatically display the time interval.

| Starting timing measurement: T-Test: Timing: Start Test                      |  |
|--|--|
| Timing measurement loading parameters setting path: T-Test: Timing: Load Set |  |
| Parameters   | Description  |
| Mode   | Loading working mode (choices: CC / CV / CP / CR / OFF)                      |
| Value  | Load setting value   |
| Starting trigger parameters setting path: T-Test: Timing: Trig. Start        |  |
| Ending trigger parameters setting path: T-Test: Timing: Trig. End            |  |
| Signal   | Trigger signal source (choices: TRI / Voltage / Current)                     |
| Edge   | Trigger methods selection (choices: rising edge (Rise)/ falling edge (Fall)) |
| Level  | Trigger voltage level  |

#### 4.10.3 Over Voltage Protection (OVP) Test

The electronic load has over voltage protection (OVP) test function. After capturing peak voltage and falling edge of the input voltage, the electronic load will start a trigger at programmed trigger voltage level ( $V_{trig}$ ) at the falling edge. And the peak voltage at the trigger voltage level point will be regarded as the measured power supply OVP point. The time interval from peak voltage occurring to trigger occurring will be the measured power supply OVP response time ( $T_{ovp}$ ). The  $T_{ovp}$  measuring accuracy is 2uS.



| Starting OVP test: T-Test: OVP Test: Start Test     |   |
|---|---|
| OVP test parameters setting path: T-Test: OVP Test: |   |
| Parameters  | Description   |
| Vtrig   | Protection Trigger voltage level, which should be higher than the output voltage level of the measured power supply under the overvoltage protection. |

#### 4.11 Automatic Test (A-Test)

Automatic test function is often used to test products in the production line. The electronic load start loading and test according to the programmed steps in the A-test files, and automatically judge if the measured power supply passed or failed the test.

You can program up to 8 files and each file is with 50 steps. The loading condition (Load), specification (SPEC) and delay time of each step can all be programmed. The delay time can be set as either waiting a trigger signal or any time ranging from 0.1S to 99S.

Loading condition supports several working modes. Each working mode is with different specification items. Please refer to the following table for the details.

| A-Test files selection: A-Test: File: List m ( $1 \leq m \leq 8$ )                          |   |
|---|---|
| Clearing A-Test files: A-Test: Clear File   |   |
| Adding a new step to A-Test file: A-Test: Edit File: New Step                               |   |
| Starting A-Test mode: A-Test: Load File   |   |
| Working mode parameters setting path: A-Test: Edit File: Step n: Load: Mode:                |   |
| Parameters  | Description   |
| CC  | Constant current mode   |
| CV  | Constant voltage mode   |
| CP  | Constant power mode   |
| CR  | Constant resistance mode  |
| DYNA  | Dynamic loading mode  |
| OCP   | OCP test mode   |
| Sweep   | Dynamic sweep mode  |
| Load Effect   | Load effect test mode   |
| LED   | LED mode  |
| Tested items parameters setting path: A-Test: Edit File: Step n: SPEC:                      |   |
| Current   | Loading current (be effective in CC,CV,CP,CR& LED working modes)                              |
| Voltage   | Input voltage (be effective in CC,CV,CP,CR& LED working modes)                                |
| Power   | Loading power (be effective in CC,CV,CP,CR& LED working modes)                                |
| Resistance  | Equivalent resistance (be effective in CC,CV,CP,CR& LED working modes)                        |
| Vpp   | Ripple voltage (be effective in CC,CV,CP,CR, DYNA & LED working modes)                        |
| Ipp   | Ripple current (be effective in CC,CV,CP,CR, DYNA & LED working modes)                        |
| Vp+   | Peak voltage (be effective in CC,CV,CP,CR, DYNA, Sweep & LED working modes)                   |
| Vp-   | Valley voltage (be effective in CC,CV,CP,CR, DYNA, Sweep & LED working modes)                 |
| Ip+   | Peak current (be effective in CC,CV,CP,CR, DYNA & LED working modes)                          |
| Ip-   | Valley current (be effective in CC,CV,CP,CR, DYNA & LED working modes)                        |
| OCP   | Over current protection (be effective in OCP mode)  |
| Pmax  | Maximum power (be effective in OCP mode)  |
| Reg.  | Load regulation (be effective in Load Effect mode)  |
| $\Delta V$  | The voltage difference when loading at Imin & Imax (be effective in Load Effect mode)         |
| Rs  | Power supply series resistance (be effective in Load Effect mode)                             |
| A-Test failing items processing methods setting path: A-Test: Setup: Fail Op.:              |   |
| Continue  | Continue to finish all the tested items even when a certain step tested item failed the test. |
| Abort   | End the automatic test immediately when a certain step tested item failed the test.           |
| A-Test trigger condition parameters setting path: A-Test: Setup: Trigger Output: Condition: |   |
| Pass  | When passing the test, initiate the trigger output (TX terminals)                             |
| Fail  | When failing the test, initiate the trigger output (TX terminals)                             |
| End   | When finishing the test, initiate the trigger output (TX terminals)                           |
| Disable   | Disable the trigger output.   |

|  |   |
|--|---|
| A-Test trigger output methods setting path: A-Test: Setup: Trigger Output: Mode: |   |
| Level  | Voltage level trigger (being effective only with low voltage level)   |
| Pulse  | Pulse trigger (low voltage level pulse. When passing the test, output pulse width is 4.2ms; when failing the test, output pulse width is 8.4ms) |
| A-Test trigger output methods setting path: A-Test: Setup: AutoRun: Volt.Trig.:  |   |
| OFF  | Disable automatic run mode of the voltage level trigger.  |
| ON   | Enable the automatic run mode of the voltage level trigger.   |

## 4.12 Battery Capacity Test (Battery)

The electronic load has battery capacity test function. Battery discharge test can be operated in CC, CR and CP mode. How to stop discharge, there are three conditions can be selected to set: voltage, capacity and time. When starting the test, the electronic load will real-time display battery discharge duration time, accumulated mAh battery capacity and WH battery capacity. When the battery voltage falls to the programmed ending voltage, the electronic load will finish the test and stop loading.

|  |  |
|--|--|
| Starting battery capacity test: Battery: Start Test                        |  |
| Battery capacity testing parameters setting path: Battery : Discharge Set: |  |
| Parameters   | Description  |
| Mode   | Discharge operation modes: CC、CP & CR modes.   |
| Value  | Loading parameters (In CC mode, value refers to current value. In CP mode, value refers to CP mode. In CR mode, value refers to resistance value.) |
| Stop condition   | Stop discharge condition   |
| Enable   | Enable the discharge condition. The ending voltage, discharge capacity and discharge time can be enabled or disabled respectively.                 |
| Voltage  | Setting the discharge stopping voltage.  |
| Capacity   | Setting the discharge stopping capacity. The unit can be Ah/Wh.  |
| Time   | Setting the discharge time. The unit is second.  |

## 4.13 Multi Loads Synchronous Control

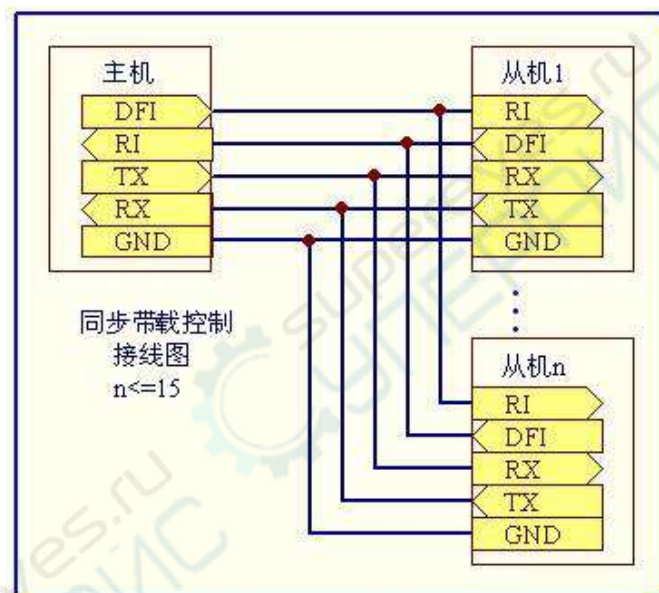
The electronic load has multi loads synchronous control function. When in synchronous control, the electronic load supports up to 16 loads Sync. loading & dynamic test, with one load as master load and other loads as slave loads, very fit for testing multi-output power supply. The addresses of slave loads cannot be the same. The effective range of the addresses is from 1 to 15. Besides, the electronic load also support up to 16 loads parallel operation for high power. In parallel operation, the electronic load will start intelligent power allocation and all the slave loads will be disabled.

After connecting the loads in parallel and setting the parameters of each load, scan the slave loads first, then initiate the master-slave synchronous control. When the master load is restarted, the slave loads will be scanned automatically once. So if master load is powered on after slave loads booting up, it is no need to scan the slave loads manually. If the slave loads are powered on or powered off, the master load will also be scanned automatically once.

|  |             |
|--|-------------|
| Scanning the slave loads: Menu: Config: Sync. Mode: Scan Slave           |             |
| Setting the addresses of slaves loads: Menu: Config: Sync. Mode: Address |             |
| Synchronous control parameters setting path: Menu: Config: Sync. Mode:   |             |
| Parameters   | Description |

|           |   |
|-----------|---|
| Sync. Run | Synchronous control. <b>ON</b> means enable the function; <b>OFF</b> means disable the function.  |
| Parallel  | Parallel control. <b>ON</b> means enable the intelligent power allocation; <b>OFF</b> means disable the intelligent power allocation.                 |
| Role      | Setting the role of the electronic load. <b>Master</b> means setting this load as master load and <b>Slave</b> means setting this load as slave load. |

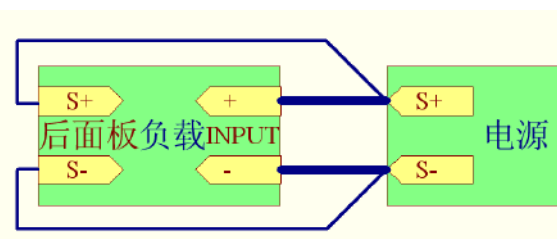
| Working Mode  | Parameters | Status |
|---|------------|--------|
| Single load mode                                    | Sync. Run  | OFF    |
| Setting the master load when in synchronous control | Sync. Run  | ON     |
|   | Parallel   | OFF    |
|   | Role       | Master |
| Setting the slave loads when in synchronous control | Sync. Run  | ON     |
|   | Parallel   | OFF    |
|   | Role       | Slave  |
| Setting the master load when in parallel operation  | Sync. Run  | ON     |
|   | Parallel   | ON     |
|   | Role       | Master |
| Setting the slave loads when in parallel operation  | Sync. Run  | ON     |
|   | Parallel   | ON     |
|   | Role       | Slave  |



## 4.14 Remote Sensing

In order to eliminate the effect of the inevitable voltage drop in the load leads, the electronic load is equipped with remote sensing, which can provide greater accuracy by allowing the load to regulate directly at the source's output terminals, as well as measure the voltage there. The connecting method is as right diagram.

If the remote sensing is enabled, the word *Sense* will be showed at the Screen.



## 4.15 Protection Functions

### 4.15.1 Over Voltage Protection

The electronic load has OVP protection. When the input voltage is 5% higher than the rated voltage, the electronic load will shut down the input immediately and display **OVER VOLT**. Meanwhile, overvoltage alarm will be triggered until the input voltage is back to the rated voltage range.

### 4.15.2 Over Current Protection

The electronic load has over current protection. When input current is higher than the programmed over current protection value, the electronic load will display **OC** and alarm once. Meanwhile, the electronic load will start loading according to the programmed over current protection value in CC mode.

### 4.15.3 Over Power Protection

The electronic load has over power protection. When input power is higher than the programmed over power protection value, the electronic load will display **OP** and alarm once. Meanwhile, the electronic load

will start loading according to the programmed over power protection value in CP mode.

#### 4.15.4 Over Temperature Protection

The electronic load has over temperature protection. Once the internal temperature exceeds 80°C, the over temperature alarm will be triggered and the electronic load will display **OVER TEMP**. Meanwhile, the electronic load will turn off the input. Users can press any key to disarm the alarm.

#### 4.15.5 Input Polarity Reversed Protection

When the input are in polarity reversed condition (will cause short circuit), the polarity reversed protection alarm will be triggered and the electronic load will display **LOC RV**. When the remote sensing is enabled, if the remote input terminals are in polarity reversed state, the electronic load will display RMT RV and the alarm will keep sounding until the polarity is correctly connected.

### 4.16 Save/Recall Setting

The electronic load supports 20 groups of data saving and recalling, including the parameters set in the system and the parameters set in basic working modes(CC / CV / CP / CR).

Saving Operation: Store n (1~20)      Recalling Operation: Recall n (1~20)

### 4.17 Rotary Knob Usage

In basic working mode, the rotary knob is used to fine-tune the setting value. Meanwhile, after pressing the rotary knob, rotating the rotary knob can fine-tune the resolution. Because there is a key hidden in the rotary knob. In Menu Operation Mode, you can also use rotary knob to select a menu quickly. At this moment, pressing the rotary knob equals pressing the **Enter** key. The function that the rotary knob fine-tunes the setting value can be disabled from the **Config** Menu.

### 4.18 Personalized Display Setting

The electronic load supports 3 display formats and display brightness adjustment. The range of display brightness adjustment is from 10 to 100. 10 is the darkest while 100 is the brightness. Besides, the electronic load also supports measuring rate adjusting so as to satisfy the different requirements.

| Adjusting the display brightness:      Menu: Config: Display: Brightness               |  |
|--|--|
| Display format setting path:      Menu: Config: Display: Format: (shortcut: <Shift+▲>) |  |
| Parameters   | Description  |
| 2 items  | Simultaneously displaying 2 measured items. The displayed characters are big.    |
| 3 items  | Simultaneously displaying 3 measured items. The displayed characters are medium. |
| 6 items  | Simultaneously displaying 6 measured items. The displayed characters are small.  |
| Adjusting the measuring rate:      Menu: Config: Measure Rate: (shortcut: <Shift+▼>)   |  |
| Parameters   | Description  |
| Fast   | Data update rate is 10Hz. Speed is fast, but stability is bad.                   |
| Medium   | Data update rate is 5Hz. Speed and stability are both medium.                    |
| Slow   | Data update rate is 2Hz. Speed is slow, but stability is good.                   |



# Chapter Five: Communication Protocol (SCPI)

## 5.1. SCPI Command Introduction

All the programming data and returned data applied to the protocol are ASCII characters. The symbol<NL> stands for “new line” and represents the ASCII coded 0A hexadecimal (or 10 decimal).

Protocols support the following data formats:

- 1) <NR1>, integer, example: 285
- 2) <NR2>, number with decimal point, example: 0.285
- 3) <NR3>, number expressed by scientific notation, example: 2.85E+2
- 4) <Nrf>, extended format, including <NR1>,<NR2>,<NR3>, example: **285**、**0.285**、**2.85E2**.
- 5) <Nrf+>, including <Nrf>, **MIN**, **MAX**, example: **285**、**0.285**、**2.85E2**、**MIN**、**MAX**. MIN and MAX are the minimum and maximum limit values that the electronic load can be set.。
- 6) <Bool>, example: **0** | **1** or **ON** | **OFF**.

Data unit should follow the data. If the unit is the default unit of the corresponding data type in the following table, then the unit can be omitted.

| Data Type  | Default unit | Support unit |
|------------|--------------|--------------|
| Voltage    | V            | mV           |
| Current    | A            | mA           |
| Power      | W            | mW           |
| Resistance | ohm          |              |
| Slew rate  | A/uS         |              |
| Time       | S            | mS           |

Some mnemonic symbols are used in SCPI protocol commands. These symbols stand for the following meaning:

| Mnemonic symbol | Meaning   |
|-----------------|---|
| < >             | In angle bracket, it should be the parameters abbreviation. |
|                 | Vertical line is used to separate the alternatives.         |
| [ ]             | In square bracket, it should be the optional items.         |

## 5.2. Register Introduction

The protocols support the following 4 registers.

### a. Questionable Status

Questionable status registers includes three 16 bits registers. They are condition register, event register and enable register. The event register captures changes in conditions corresponding to condition bits in a condition register. An event (QUES bit in the status byte register) becomes true when the corresponding condition bits of the enable register is enabled. Reading an event registers clears the register (all bits set to zero). Condition register is defined as follows:

| Bit   | Name | Meaning   |
|-------|------|---|
| Bit0  | VF   |   |
| Bit1  | OC   | The electronic load is in over current condition.             |
| Bit3  | OP   | The electronic load is in over power condition.               |
| Bit4  | OT   | The electronic load is in over temperature condition.         |
| Bit8  | RRV  | The electronic load is in remote polarity reversed condition. |
| Bit11 | UNR  |   |

|       |     |  |
|-------|-----|--|
| Bit12 | LRV | The electronic load is in local polarity reversed condition. |
| Bit13 | OV  | The electronic load is in over voltage condition.            |

#### b. Standard Event Status

The standard event status registers includes two 16 bits registers: event register and enable register. An event (ESB bit in the status byte register) becomes true if the corresponding condition bit of enable register is enabled. Reading of the standard event status register will reset it to zero. Event register is defined as follows:

| Bit  | Name | Meaning                              |
|------|------|--------------------------------------|
| Bit0 | OPC  | Operation is completed.              |
| Bit2 | QYE  | Query error occurs.                  |
| Bit3 | DDE  | Device dependent error occurs.       |
| Bit4 | EXE  | Execution error occurs.              |
| Bit5 | CME  | Command error occurs.                |
| Bit7 | PON  | The electronic load is repowered on. |

#### c. Operation Status

The operation status registers includes three 16 bits registers: condition register, event register and enable register. The event register captures changes in conditions corresponding to condition bits in a condition register. An event (OPER bit in the status byte register) becomes true when the corresponding condition bits of the enable register is enabled. Reading an event registers clears the register (all bits set to zero). Condition register is defined as follows:

| Bit  | Name | Meaning  |
|------|------|--|
| Bit0 | CAL  | The electronic load is in calibration condition.           |
| Bit5 | WTG  | The electronic load is in waiting for a trigger condition. |

#### d. Status Byte

The status byte registers includes two 8 bits registers: event register and enable register. An event (RQS bit in the status byte register) becomes true if the corresponding condition bit of enable register is enabled. Reading an event registers clears the register (all bits set to zero). Event register is defined as follows:

| Bit  | Name | Meaning   |
|------|------|---|
| Bit3 | QUES | Questionable. It indicates if an enabled questionable event has occurred. |
| Bit4 | MAV  | Message available. It indicates if the output queue contains data.        |
| Bit5 | ESB  | Event status bit. It indicates if an enabled standard event has occurred. |
| Bit6 | RQS  |   |
| Bit7 | OPER |   |

## 5.3. Common Commands

### \*CLS: Clear Status Command

The CLS command executes the following actions: clear these registers.

- Standard Event Status Event Register
- Questionable Status Event Register
- Operation Status Event Register
- Status Byte Event Register

## Error Queue

**Command Syntax:** \*CLS

**\*ESE Standard Event Status Enable Command/Query**

This command sets the condition of the standard event status enable register, which determines which events of the standard event status event register are allowed to set the ESB (Event Summary Bit) of the status byte register. A “1” in the bit position enables the corresponding event.

**Command Syntax:** \*ESE <NRf>

**Parameters:** 0~255

**Power On Value** Refer to \*PSC command

**Example:** \*ESE 128

**Query Syntax:** \*ESE?

**Return Parameters** <NR1>

**\*ESR? Standard Event Status Register Query**

This query reads the standard event status register. After reading the register, the register will be cleared as zero. The bits in the standard event status register are defined as the same with those in the standard event status enable register.

**Query Syntax:** \*ESR?

**Return Parameters:** <NR1>

**\*IDN? Identification Query**

This query requests the electronic load to identify itself. Its return parameters include four strings separated by comma.

**Query Syntax:** \*IDN?

| Return Parameters: <AARD> Strings           | Description      |
|---|------------------|
| JARTUL                                      | Manufacture      |
| JT632xA                                     | Model            |
| xxxxxxxxx                                   | Serial No.       |
| x.xx.xx                                     | Software edition |
| Example: JARTUL, JT6321A,xxxxxxxxx, A.01.02 |                  |

**\*OPC Operation Complete Command**

This command causes the interface to set the OPC bit of the standard event status register as “1” when the electronic load has completed all pending operations.

**Command Syntax:** \*OPC

**Query Syntax:** \*OPC?

**Return Parameters:** <NR1>

**\*PSC Power-on Status Clear Command**

This command controls the automatic clearing of the status byte enable register, the operation status enable register, the questionable status enable Register and the standard event status enable register when the electronic load is re-powered on.

**1 or ON** This choice enables the power-on clearing of the listed registers.

**0 or OFF** This choice disable the clearing of the listed registers and they retain their status when a power-on condition occurs.

**Command Syntax:** \*PSC <bool>

**Parameters:** 0|1|ON|OFF

**Query Syntax:** \*PSC?

**Return Parameters:** 0|1

**\*RCL Recall Instrument State Command**



This command restores the electronic load to a state that was previously stored in memory.

**Command Syntax:** \*RCL <NR1>

**Parameters:** 1~20

**Example:** \*RCL 3

#### **\*RST Reset Command**

This command resets the state of the electronic load to its factory default.

**Command Syntax:** \*RST

**Parameters:** None

#### **\*SAV Save Command**

This command stores the present state of the electronic load to a specified location in memory.

**Command Syntax:** \*SAV <NR1>

**Parameters:** 1~20

**Example:** \*SAV 3

#### **\*SRE Service Request Enable Command/Query**

This commands sets the condition of the service request enable register, which determines which events of the status byte register are allowed to set RQS of the status byte register. A “1” in the bit position enables the corresponding event. The bits in the status byte enable register are defined as the same with those in the status byte register.

**Command Syntax:** \*SRE <NRf>

**Parameters:** 0~255

**Power-on Value:** Refer to \*PSC command

**Example:** \*SRE 128

**Query Syntax:** \*SRE ?

**Return Parameters:** <NR1>

#### **\*STB? Read Status Byte Query**

This command reads the status byte register. The status byte register is cleared to be zero when this command is executed.

**Query Syntax:** \*STB ?

**Return Parameters:** <NR1>

#### **\*TST? Self-test Query**

These command requests the electronic load make internal self-test and report the errors.

## 5.4. Required Command

### 5.4.1. System Command

#### **SYSTem:ERRor?**

This command is used to query the error information.

**Query Syntax:** SYSTem:ERRor[:NEXT]?

**Return Parameters:** <NR1>, <SRD>

**Example:** SYST:ERR?

#### **SYSTem:VERSion?**

This command is used to query the SCPI version applied to the electronic load. Its format is YYYY.V

**Query Syntax:** SYSTem:VERSion?

**Return Parameters:** <NR1>, <SRD>

**Example:** SYST:VERS?

#### **SYSTem:SENSe**

This command is used to turn on or turn off the remote sensing function.

**Command Syntax:** SYSTem:SENSe[:STATe] <bool>  
**Parameters:** 0 | 1 | OFF | ON  
**Reset Value:** OFF  
**Example:** SYST:SENS ON  
**Query Syntax:** SYSTem:SENSe[:STATe]?  
**Return Parameters:** 0 | 1

#### **SYSTem:BEEPer:STATe**

This command is used to enable or disable the buzzer.

**Command Syntax:** SYSTem:BEEPer:STATe <bool>  
**Parameters:** 0 | 1 | OFF | ON  
**Reset Value:** OFF  
**Example:** SYST:BEEP:STAT ON  
**Query Syntax:** SYSTem:BEEPer:STATe?  
**Return Parameters:** 0 | 1

#### **SYSTem:LOCAl**

This command is used to enable the local operation. All the keys at the front panel of the load are enabled for operation.

**Command Syntax:** SYSTem:LOCAl  
**Example:** SYST:LOC

#### **SYSTem:REMote**

This command is used to enable the remote operation. Except the key *Shift-Local*, all other keys at the front panel of the load are disabled for operation. Exit the remote operation by pressing the key *Shift-Local*.

**Command Syntax:** SYSTem:REMote  
**Example:** SYST:REM

#### **SYSTem:RWLock**

This command is used to enable the remote operation. All keys at the front panel of the load, including the key *Shift-Local*, are disabled for operation. Exit the remote operation to local operation by using the command *SYSTem:LOCAl*.

**Command Syntax:** SYSTem:RWLock  
**Example:** SYST:RWL

### 5.4.2. Status Command

#### **STATus:QUEStionalbe?**

This command is used to read the event register in the questionable status register.

**Query Syntax:** STATus:QUEStionalbe[:EVENT]?  
**Example:** STAT:QUES:EVEN?  
**Return Parameters:** <NR1>

#### **STATus:QUEStionalbe:CONDition?**

This command is used to read the condition register in the questionable status register.

**Query Syntax:** STATus:QUEStionalbe:CONDition?  
**Example:** STAT:QUES:COND?  
**Return Parameters:** <NR1>

#### **STATus:QUEStionalbe:ENABle**

This command is used to set or read the enable register in the questionable status register.

**Command syntax:** STATus:QUEStionalbe <NRf+>

|                           |                             |
|---------------------------|-----------------------------|
| <b>Parameters:</b>        | 0 ~ 32767                   |
| <b>Example:</b>           | STAT:QUES:ENAB 32           |
| <b>Query Syntax:</b>      | STATus:QUESTionalbe:ENABLE? |
| <b>Return Parameters:</b> | <NR1>                       |

**STATus:OPERation?**

This command is used to read the event register in the operation status register.

|                           |                           |
|---------------------------|---------------------------|
| <b>Query Syntax:</b>      | STATus:OPERation[:EVENT]? |
| <b>Example:</b>           | STAT:OPER:EVEN?           |
| <b>Return Parameters:</b> | <NR1>                     |

**STATus: OPERation:CONDition?**

This command is used to read the condition register in the operation status register.

|                           |                             |
|---------------------------|-----------------------------|
| <b>Query Syntax:</b>      | STATus:OPERation:CONDition? |
| <b>Example:</b>           | STAT:OPER:COND?             |
| <b>Return Parameters:</b> | <NR1>                       |

**STATus: OPERation:ENABLE**

This command is used to set or read the enable register in the operation status register.

|                           |                          |
|---------------------------|--------------------------|
| <b>Command Syntax:</b>    | STATus:OPERation <NRf+>  |
| <b>Parameters:</b>        | 0 ~ 32767                |
| <b>Example:</b>           | STAT: OPER:ENAB 32       |
| <b>Query Syntax:</b>      | STATus:OPERation:ENABLE? |
| <b>Return Parameters:</b> | <NR1>                    |

## 5.5. Input Setup Command

### 5.5.1. Input control

**[SOURce:]INPut**

This command is used to turn on or off the input.

|                           |                               |
|---------------------------|-------------------------------|
| <b>Command syntax:</b>    | [SOURce:]INPut[:STATe] <bool> |
| <b>Parameters:</b>        | 0   1   OFF   ON              |
| <b>Reset Value:</b>       | OFF                           |
| <b>Example:</b>           | INP 1                         |
| <b>Query Syntax:</b>      | INPut[:STATe]?                |
| <b>Return Parameters:</b> | 0   1                         |

**[SOURce:]INPut:SHORT**

This command is used to enable or disable the short-circuit of the input.

|                           |                             |
|---------------------------|-----------------------------|
| <b>Command Syntax:</b>    | [SOURce:]INPut:SHORT <bool> |
| <b>Parameters:</b>        | 0   1   OFF   ON            |
| <b>Reset Value:</b>       | OFF                         |
| <b>Example:</b>           | INP:SHOR 1                  |
| <b>Query Syntax:</b>      | INPut:SHORT?                |
| <b>Return Parameters:</b> | 0   1                       |

### 5.5.2. System Parameters Setup

**[SOURce:]CURRent:RANGe**

This command is the set the current range. When the set current is in low current range please select the low current range; otherwise select the high current range.

|                        |                               |
|------------------------|-------------------------------|
| <b>Command Syntax:</b> | [SOURce:]CURRent:RANGe <NRf+> |
| <b>Parameters:</b>     | 0 ~ MAX   MINimum   MAXimum   |

|                           |                              |
|---------------------------|------------------------------|
| <b>Unit:</b>              | A                            |
| <b>Reset Value:</b>       | MAXimum (high current range) |
| <b>Example:</b>           | CURR:RANGE MIN               |
| <b>Query Syntax:</b>      | [SOURce:]CURRent:RANGe?      |
| <b>Return Parameters:</b> | <NR2>                        |

**[SOURce:]VOLTage:RANGe**

This command is used to set the voltage range. When the set voltage is in low voltage range please select the low voltage range; otherwise select the high voltage range.

|                           |                               |
|---------------------------|-------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]VOLTage:RANGe <NRf+> |
| <b>Parameters:</b>        | 0 ~ MAX   MINimum   MAXimum   |
| <b>Unit:</b>              | V                             |
| <b>Reset Value:</b>       | MAXimum (high voltage range)  |
| <b>Example:</b>           | SOUR:VOLT:RANGE MIN           |
| <b>Query Command:</b>     | [SOURce:]VOLTage:RANGe?       |
| <b>Return Parameters:</b> | <NR2>                         |

**[SOURce:]CURRent:SLEW**

This command is used to set the same current rising and falling slew rate.

|                           |                                       |
|---------------------------|---------------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]CURRent:SLEW[:BOTH] <NRf+>   |
| <b>Parameters:</b>        | MIN ~ MAX   MINimum   MAXimum         |
| <b>Unit:</b>              | A/s                                   |
| <b>Reset Value:</b>       | MAXimum                               |
| <b>Example:</b>           | CURR:SLEW 300000<br>CURR:SLEW 0.3A/uS |
| <b>Query Syntax:</b>      | [SOURce:]CURRent:SLEW?                |
| <b>Return Parameters:</b> | <NR2>                                 |

**[SOURce:]CURRent:SLEW:RISE**

This command is used to set the current rising slew rate.

|                           |                                   |
|---------------------------|-----------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]CURRent:SLEW:RISE <NRf+> |
| <b>Parameters:</b>        | MIN ~ MAX   MINimum   MAXimum     |
| <b>Unit:</b>              | A/s                               |
| <b>Reset Value:</b>       | MAXimum                           |
| <b>Example:</b>           | CURR:SLEW:RISE 3000               |
| <b>Query Syntax:</b>      | [SOURce:]CURRent:SLEW:RISE?       |
| <b>Return Parameters:</b> | <NR2>                             |

**[SOURce:]CURRent:SLEW:FALL**

This command is used to set the current falling slew rate.

|                           |                                   |
|---------------------------|-----------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]CURRent:SLEW:FALL <NRf+> |
| <b>Parameters:</b>        | MIN ~ MAX   MINimum   MAXimum     |
| <b>Unit:</b>              | A/s                               |
| <b>Reset Value:</b>       | MAXimum                           |
| <b>Example:</b>           | CURR:SLEW:FALL 3000               |
| <b>Query Syntax:</b>      | [SOURce:]CURRent:SLEW:FALL?       |
| <b>Return Parameters:</b> | <NR2>                             |

**[SOURce:]CURRent:PROTection**

This command is used to set the current protection value.

|                        |  |
|------------------------|--|
| <b>Command Syntax:</b> | [SOURce:]CURRent:PROTection[:LEVel] <NRf+> |
|------------------------|--|

|                           |                                      |
|---------------------------|--------------------------------------|
| <b>Parameters:</b>        | 0 ~ MAX   MINimum   MAXimum          |
| <b>Unit:</b>              | A                                    |
| <b>Reset Value:</b>       | MAXimum                              |
| <b>Example:</b>           | CURR:PROT 3                          |
| <b>Query Syntax:</b>      | [SOURce:]CURRent:PROTection[:LEVel]? |
| <b>Return Parameters:</b> | <NR2>                                |

**[SOURce:]POWer:PROTection**

This command is used to set the power protection value.

|                           |  |
|---------------------------|--|
| <b>Command Syntax:</b>    | [SOURce:]POWer:PROTection[:LEVel] <NRf+> |
| <b>Parameters:</b>        | 0 ~ MAX   MINimum   MAXimum              |
| <b>Unit:</b>              | V  |
| <b>Reset Value:</b>       | MAXimum (high range)                     |
| <b>Example:</b>           | POW:PROT 100                             |
| <b>Query Syntax:</b>      | [SOURce:] POWer:PROTection[:LEVel]?      |
| <b>Return Parameters:</b> | <NR2>                                    |

**[SOURce:]VOLTage:[LEVel:]ON**

This command is used to set the Von value of the electronic load.

|                           |                                    |
|---------------------------|------------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]VOLTage:[LEVel:]ON <NRf+> |
| <b>Parameters:</b>        | 0 ~ MAX   MINimum   MAXimum        |
| <b>Unit:</b>              | V                                  |
| <b>Reset Value:</b>       | 1                                  |
| <b>Example:</b>           | VOLT:ON 3                          |
| <b>Query Syntax:</b>      | [SOURce:] VOLTage:[LEVel:]ON?      |
| <b>Return Parameters:</b> | <NR2>                              |

**[SOURce:]VOLTage:[LEVel:]OFF**

This command is used to set the Voff value of the electronic load.

|                           |                                     |
|---------------------------|-------------------------------------|
| <b>Command Syntax:</b>    | [SOURce:]VOLTage:[LEVel:]OFF <NRf+> |
| <b>Parameters:</b>        | 0 ~ MAX   MINimum   MAXimum         |
| <b>Unit:</b>              | V                                   |
| <b>Reset Value:</b>       | 0.5                                 |
| <b>Example:</b>           | VOLT:OFF 2                          |
| <b>Query Syntax:</b>      | [SOURce:] VOLTage:[LEVel:]OFF?      |
| <b>Return Parameters:</b> | <NR2>                               |

**5.5.3. Working Mode Control****[SOURce:]FUNCTION****[SOURce:]MODE**

These two commands have the same function. Both are used to select the input working mode of the electronic load.

|                        |                              |
|------------------------|------------------------------|
| <b>Command Syntax:</b> | [SOURce:]FUNCTION <function> |
|                        | [SOURce:]MODE <function>     |

| Parameters | Working Mode             |
|------------|--------------------------|
| CURRent    | Constant Current Mode    |
| VOLTage    | Constant Voltage Mode    |
| POWer      | Constant Power Mode      |
| RESistance | Constant Resistance Mode |
| DYNAmic    | Dynamic Operation Mode   |

| LED                       | LED Mode                             |
|---------------------------|--------------------------------------|
| <b>Reset Value:</b>       | CURRent                              |
| <b>Example:</b>           | FUNC RES<br>MODE RES                 |
| <b>Query Syntax:</b>      | [SOURce:]FUNCtion?<br>[SOURce:]MODE? |
| <b>Return Parameters:</b> | <CRD>                                |

#### 5.5.4. Working Parameters Setup

##### [SOURce:]CURRENT

This command is used to set the current in CC mode.

##### Command Syntax:

[SOURce:]CURRent[:LEVel][:IMMEDIATE][:AMPLitude] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** A

**Reset Value:** MINimum

**Example:** CURR 5

**Query Syntax:** [SOURce:]CURRent[:LEVel][:IMMEDIATE][:AMPLitude]?

**Return Parameters:** <NR2>

##### [SOURce:]VOLTage

This command is used to set the voltage in CV mode.

##### Command Syntax:

[SOURce:]VOLTage[:LEVel][:IMMEDIATE][:AMPLitude] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** V

**Reset Value:** MAXimum

**Example:** VOLT 5

**Query Command:** [SOURce:]VOLTage[:LEVel][:IMMEDIATE][:AMPLitude]?

**Return Parameters:** <NR2>

##### [SOURce:]POWER

This command is used to set the power in CP mode.

##### Command syntax:

[SOURce:]POWER[:LEVel][:IMMEDIATE][:AMPLitude] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** W

**Reset Value:** MINimum

**Example:** POW 10

**Query Syntax:** [SOURce:]POWER[:LEVel][:IMMEDIATE][:AMPLitude]?

**Return Parameters:** <NR2>

##### [SOURce:]RESistance

This command is used to set the resistance in CR mode.

##### Command Syntax:

[SOURce:]RESistance[:LEVel][:IMMEDIATE][:AMPLitude] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** ohm

**Reset Value:** MAXimum

**Example:** RES 5



**Query Syntax:** [SOURce:]RESistance[:LEVel][:IMMEDIATE][:AMPLitude]?

**Return Parameters:** <NR2>

#### [SOURce:]CURRENT:DYNAMIC:HIGH

This command is used to set the high-level loading current in dynamic mode.

**Command Syntax:** [SOURce:]DYNAMIC:HIGH[:LEVel] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** A

**Reset Value:** 0

**Example:** CURR:DYN:HIGH 10

**Query Syntax:** [SOURce:] DYNAMIC:HIGH[:LEVel]?

**Return Parameters:** <NR2>

#### [SOURce:]CURRENT:DYNAMIC:HIGH:DWELL

This command is used to set the dwelling time of the high-level loading current in dynamic mode.

**Command Syntax:** [SOURce:] DYNAMIC:HIGH:DWELL <NRf+>

**Parameters:** 0.00002 ~ 0.999 | MINimum | MAXimum

**Unit:** s

**Reset Value:** 0.00002

**Example:** CURR:DYN:HIGH:DWELL 10

**Query Syntax:** [SOURce:] DYNAMIC:HIGH:DWELL?

**Return Parameters:** <NR2>

#### [SOURce:]CURRENT:DYNAMIC:LOW

This command is used the low-level loading current in dynamic mode.

**Command Syntax:** [SOURce:] DYNAMIC:LOW[:LEVel] <NRf+>

**Parameters:** 0 ~ MAX | MINimum | MAXimum

**Unit:** A

**Reset Value:** 0

**Example:** CURR:DYN:LOW 1

**Query Syntax:** [SOURce:] DYNAMIC:LOW[:LEVel]?

**Return Parameters:** <NR2>

#### [SOURce:]CURRENT:DYNAMIC:LOW:DWELL

This command is used to set the dwelling time of the low-level loading current in dynamic mode.

**Command Syntax:** [SOURce:] DYNAMIC:LOW:DWELL <NRf+>

**Parameters:** 0.00002 ~ 0.999 | MINimum | MAXimum

**Unit:** s

**Reset Value:** 0.00002

**Example:** CURR:DYN:LOW:DWELL 10

**Query Syntax:** [SOURce:] DYNAMIC:LOW:DWELL?

**Return Parameters:** <NR2>

#### [SOURce:]CURRENT:DYNAMIC:SLEW

This command is used to set the same current rising and falling slew rate in dynamic mode.

**Command Syntax:** [SOURce:] DYNAMIC:SLEW <NRf+>

**Parameters:** MIN ~ MAX | MINimum | MAXimum

**Unit:** A/s

**Reset Value:** MAX

**Example:** CURR:DYN:SLEW 30000

**Query Syntax:** [SOURce:] DYNAMIC:SLEW?

**Return Parameters:** < NR2>

#### **[SOURCE:]CURRENT:DYNAMIC:SLEW:RISE**

This command is used to set the current rising slew rate in dynamic mode.

**Command Syntax:** [SOURCE:] DYNAMIC:SLEW:RISE <NRF+>

**Parameters:** MIN ~ MAX | MINimum | MAXimum

**Unit:** A/s

**Reset Value:** MAX

**Example:** CURR:DYN:SLEW 30000

**Query Syntax:** [SOURCE:] DYNAMIC:SLEW:RISE?

**Return Parameters:** < NR2>

#### **[SOURCE:]CURRENT:DYNAMIC:SLEW:FALL**

This command is used to set the current falling slew rate in dynamic mode.

**Command Syntax:** [SOURCE:] DYNAMIC:SLEW:FALL <NRF+>

**Parameters:** MIN ~ MAX | MINimum | MAXimum

**Unit:** A/s

**Reset Value:** MAX

**Example:** CURR:DYN:SLEW:FALL 30000

**Query Syntax:** [SOURCE:] DYNAMIC:SLEW:FALL?

**Return Parameters:** < NR2>

#### **[SOURCE:]CURRENT:DYNAMIC:MODE**

This command is used to set the working mode in dynamic mode.

**Command Syntax:** [SOURCE:] DYNAMIC:MODE <mode>

**Parameters:** CONTinuous | PULSe | TOGGle

**Reset Value:** CONTinuous

**Example:** CURR:DYN:MODE PULS

**Query Syntax:** [SOURCE:] DYNAMIC:MODE?

**Return Parameters:** <CRD>

#### **LED:VOLTage**

This command is used to set LED Vo.

**Command Syntax:** LED:VOLTage <NRF+>

**Parameters:** 0.001~MAX

**Example:** LED:VOLT 18

**Query Syntax:** LED:VOLT?

**Return Parameters:** <NR2>

#### **LED:CURRENT**

This command is used to set LED Io.

**Command Syntax:** LED:CURRENT <NRF+>

**Parameters:** 0~MAX

**Example:** LED:CURR 0.35

**Query Syntax:** LED:CURR ?

**Return Parameters:** <NR2>

#### **LED:RCOeff**

This command is used to set LED Rd Coeff.

**Command Syntax:** LED:RCOeff <NRF+>

**Parameters:** 0.001~1

**Example:** LED:RCO 0.2



**Query Syntax:** LED:RCO?

**Return Parameters:** <NR2>

## 5.6. Measure Command

### MEASure:VOLTage?

This command is used to read the average voltage.

**Command Syntax:** MEASure[:SCALar]:VOLTage[:DC]?

**Example:** MEAS:VOLT?

**Return Parameters:** <NR2>

### MEASure:VOLTage:MAXimum?

This command is used to read the peak voltage  $V_{p+}$ .

**Command Syntax:** MEASure[:SCALar]:VOLTage:MAXimum?

**Example:** MEAS:VOLT:MAX?

**Return Parameters:** <NR2>

### MEASure:VOLTage:MINimum?

This command is used to read the valley voltage  $V_{p-}$ .

**Command Syntax:** MEASure[:SCALar]:VOLTage:MINimum?

**Example:** MEAS:VOLT:MIN?

**Return Parameters:** <NR2>

### MEASure:VOLTage:PTPeak?

This command is used to read the peak to peak voltage  $V_{pp}$ .

**Command Syntax:** MEASure[:SCALar]:VOLTage:PTPeak?

**Example:** MEAS:VOLT:PTP?

**Return Parameters:** <NR2>

### MEASure:CURREnt?

This command is used to read the average current.

**Command Syntax:** MEASure[:SCALar]:CURREnt[:DC]?

**Example:** MEAS:CURR?

**Return Parameters:** <NR2>

### MEASure: CURREnt:MAXimum?

This command is used to read the peak current  $V_{p+}$ .

**Command Syntax:** MEASure[:SCALar]:CURREnt:MAXimum?

**Example:** MEAS:CURR:MAX?

**Return Parameters:** <NR2>

### MEASure: CURREnt:MINimum?

This command is used to read the valley current  $V_{p-}$ .

**Command Syntax:** MEASure[:SCALar]:CURREnt:MINimum?

**Example:** MEAS:CURR:MIN?

**Return Parameters:** <NR2>

### MEASure:CURREnt:PTPeak?

This command is used to read peak to peak current  $I_{pp}$ .

**Command Syntax:** MEASure[:SCALar]:CURREnt:PTPeak?

**Example:** MEAS:CURR:PTP?

**Return Parameters:** <NR2>

### MEASure:POWER?

This command is used to read average power.

**Command Syntax:** MEASure[:SCALAr]:POWer[:DC]?

**Example:** MEAS:POWer?

**Return Parameters:** <NR2>

#### MEASure:RESistance?

This command is used to read equivalent resistance.

**Command Syntax:** MEAS[:SCALAr]:RESistance[:DC]?

**Example:** MEAS:RESistance?

**Return Parameters:** <NR2>

## 5.7. OCP Test Command

#### OCP[:STATe]

This command is used to start or stop OCP test.

**Command Syntax:** OCP[:STATe] <bool>

**Parameters:** 0 | 1 | OFF | ON

**Example:** OCP ON

**Query Syntax:** OCP[:STATe]?

**Return:** 0 | 1

#### OCP:ISart

This command is used to set the starting current of the OCP test.

**Command Syntax:** OCP:ISart <NRf+>

**Parameters:** 0 ~ MAX

**Unit:** A

**Example:** OCP:IST 3

**Query Syntax:** OCP:ISart?

**Return:** <NR2>

#### OCP:IEND

This command is used to set the ending current of the OCP test.

**Command Syntax:** OCP:IEND <NRf+>

**Parameters:** 0 ~ MAX

**Unit:** A

**Example:** OCP:IEND 6

**Query Syntax:** OCP:IEND?

**Return:** <NR2>

#### OCP:STEP

This command is used to set the current rising steps of the OCP test.

**Command Syntax:** OCP:STEP <NR1>

**Parameters:** 1 ~ 1000

**Example:** OCP:STEP 500

**Query Syntax:** OCP:STEP?

**Return:** <NR2>

#### OCP:DWELI

This command is used to set the single step dwelling time of the OCP test.

**Command Syntax:** OCP:DWELI <NRf+>

**Parameters:** 0.00001 ~ 0.99999

**Unit:** S

**Example:** OCP:DWEL 0.01 or OCP:DWEL 10ms

**Query Syntax:** OCP:DWEL?

**Return:** <NR2>

#### **OCP:VTRig**

This command is used to set the trigger voltage level of the OCP test.

**Command Syntax:** OCP:VTRig <NRf+>

**Parameters:** 0 ~ MAX

**Unit:** V

**Example:** OCP:VTR 11.8

**Query Syntax:** OCP:VTRig?

**Return:** <NR2>

#### **OCP:RESult[:OCP]**

This command is used to query the current at OCP point.

**Command Syntax:** OCP:RESult[:OCP]?

**Parameters:** <NRf+>

-1 means the test has not finished yet.

-2 means the voltage of the measured power supply doesn't drop to the Vtrig, i.e. OCP isn't initiated.

**Unit:** A

**Example:** OCP:RES?

**Return:** 4.68

#### **OCP:RESult:PMAX**

This command is used to query Pmax point.

**Command Syntax:** OCP:RESult:PMAX?

**Parameters:** <NR2>, <NR2>, <NR2>

**Unit:** W, V, A

**Example:** OCP:RES:PMAX?

**Return:** 55.34, 11.8, 4.69

Means the maximum power at Pmax point is 55.34W and the voltage and current at Pmax point is 11.8V & 4.69A respectively.

## 5.8. OVP Test Command

**OVP[:STATe]** This command is used to start or stop OVP test.

**Command Syntax:** OVP[:STATe] <bool>

**Parameters:** 0 | 1 | OFF | ON

**Example:** OVP ON

**Query Syntax:** OVP[:STATe]?

**Return:** 0 | 1

#### **OVP:VTRig**

This command is used to set OVP trigger level.

**Command Syntax:** OVP:VTRig <NRf+>

**Parameters:** 0 ~ MAX

**Unit:** V

**Example:** OVP:VTR 4

**Query Syntax:** OVP:VTRig?

**Return:** <NR2>

#### **OVP:RESult[:OVP]**

This command is used to query the voltage value at OVP point.

**Command Syntax:** OVP:RESult[:OVP]?

**Return Parameters:** <NRf+>  
 -1 means the test has not been finished yet.  
 -2 means OVP test has not been started yet.

**Unit:** V

**Example:** OVP:RES?

**Return:** 6.68

**OVP:RESult:TIME** This command is used to query tovp

**Command Syntax:** OVP:RESult:TIME?

**Return Parameters:** <NR2>

**Unit:** S

**Example:** OVP:RES:TIME?

**Return:** 0.126

## 5.9. Timing Measurement Command

### TIMing[:STATe]

This command is used to start or stop Timing Measurement.

**Command Syntax:** TIMing[:STATe] <bool>

**Parameters:** 0 | 1 | OFF | ON

**Example:** TIM ON

**Query Syntax:** TIMing[:STATe]?

**Return:** 0 | 1

### TIMing:LOAD:SETTing

This command is used to confirm if the load setup is changed in timing measurement.

**命令语法** TIMing:LOAD:SETTing <bool>

**参数** 0 | 1 | OFF | ON

ON means when the timing measurement is started, the load setup will be changed according to the setup in TIMing:LOAD and when the timing measurement is finished, the load input will be off.

OFF means the load setup will not be changed when the timing measurement is started or finished.

**例子** TIM:LOAD:SETT OFF

**查询语法** TIMing:LOAD:MODE?

**返回** <mode>

### TIMing:LOAD:MODE

This command is used to set the loading mode of the timing measurement

**Command Syntax:** TIMing:LOAD:MODE <mode>

**Parameters:** CURR | VOLT | POW | RES | OFF

**Example:** TIM:LOAD:MODE CURR

**Query Syntax:** TIMing:LOAD:MODE?

**Return:** <mode>

**Related Command:** If there is the command *TIM:LOAD:SETT OFF*, then the command *TIMing:LOAD:MODE* can be ignored.

### TIMing:LOAD:VALue

This command is used to set the loading parameters of the timing measurement.

**Command Syntax:** TIMing:LOAD:VALue <Nrf+>

|                         |   |
|-------------------------|---|
| <b>Parameters:</b>      | A / V / W / ohm, depends on TIMing:LOAD:MODE  |
| <b>Example:</b>         | TIM:LOAD:VAL 1  |
| <b>Query Syntax:</b>    | TIMing:LOAD:VALue?  |
| <b>Return:</b>          | <NR2>   |
| <b>Related Command:</b> | If there is the command <i>TIM:LOAD:SETT OFF</i> , then the command <i>TIMing:LOAD:MODE</i> can be ignored. |

**TIMing:TStart:SOURce**

This command is used to set the trigger source of the start-up test.

|                        |                               |
|------------------------|-------------------------------|
| <b>Command Syntax:</b> | TIMing:TStart:SOURce <source> |
| <b>Parameters:</b>     | VOLT   CURR   EXT             |
| <b>Example:</b>        | TIM:TST:SOUR VOLT             |
| <b>Query Syntax:</b>   | TIMing:TStart:SOURce?         |
| <b>Return:</b>         | <source>                      |

**TIMing:TStart:EDGE**

This command is used to set the trigger edge of the start-up test.

|                        |                           |
|------------------------|---------------------------|
| <b>Command Syntax:</b> | TIMing:TStart:EDGE <edge> |
| <b>Parameters:</b>     | RISE   FALL               |
| <b>Example:</b>        | TIM:TST:EDGE RISE         |
| <b>Query Syntax:</b>   | TIMing:TStart:EDGE?       |
| <b>Return:</b>         | <edge>                    |

**TIMing:TStart:LEVel**

This command is used to set the trigger voltage level of the start-up test.

|                        |   |
|------------------------|---|
| <b>Command Syntax:</b> | TIMing:TStart:LEVel <Nrf+>  |
| <b>Parameters:</b>     | depends on the start-up trigger source, that is, TIMing:TStart:SOURce |
| <b>Example:</b>        | TIM:TST:LEV 1   |
| <b>Query Syntax:</b>   | TIMing:TStart:LEVel?  |
| <b>Return:</b>         | <NR2>   |

**TIMing:TEND:SOURce**

This command is used to set the trigger source of ending the test.

|                        |                             |
|------------------------|-----------------------------|
| <b>Command Syntax:</b> | TIMing:TEND:SOURce <source> |
| <b>Parameters:</b>     | VOLT   CURR   EXT           |
| <b>Example:</b>        | TIM:TEND:SOUR VOLT          |
| <b>Query Syntax:</b>   | TIMing:TEND:SOURce?         |
| <b>Return:</b>         | <source>                    |

**TIMing:TEND:EDGE**

This command is used to set the trigger edge of ending the test.

|                        |                         |
|------------------------|-------------------------|
| <b>Command Syntax:</b> | TIMing:TEND:EDGE <edge> |
| <b>Parameters:</b>     | RISE   FALL             |
| <b>Example:</b>        | TIM:TEND:EDGE RISE      |
| <b>Query Syntax:</b>   | TIMing:TEND:EDGE?       |
| <b>Return:</b>         | <edge>                  |

**TIMing:TEND:LEVel**

This command is used to set the trigger voltage level of ending the test.

|                        |   |
|------------------------|---|
| <b>Command Syntax:</b> | TIMing:TEND:LEVel <Nrf+>                                  |
| <b>Parameters:</b>     | depends on the trigger source, that is TIMing:TEND:SOURce |
| <b>Example:</b>        | TIM:TEND:LEV 1  |

**Query Syntax:** TIMing:TEND:LEVel?

**Return:** <NR2>

#### **TIMing:RESult**

This command is used to query the result of the Timing measurement.

**Command Syntax:** TIMing:RESult?

**Unit:** S

**Example:** TIM:RES?

**Return:** <NR2>

## 5.10. Peak Test Command

Peak command can be used to read the maximum/ minimum value and clear the Peak Value Record automatically when the test is started.

**PEAK[:STATe]** This command is used to start or stop the peak value test.

**Command Syntax:** PEAK[:STATe] <bool>

**Example:** PEAK ON

**PEAK:CLEAr** This command is used to clear the peak value record.

**Command Syntax:** PEAK:CLEAr

**Example:** PEAK:CLE

**PEAK:VOLTage:MAXimum?** This command is used to read the maximum voltage.

**Command Syntax:** PEAK:VOLTage:MAXimum?

**Example:** PEAK:VOLT:MAX?

**Return Parameters:** <NR2>

**PEAK:VOLTage:MINimum?** This command is used to read the minimum voltage.

**Command Syntax:** PEAK:VOLTage:MINimum?

**Example:** PEAK:VOLT:MIN?

**Return Parameters:** <NR2>

**PEAK:CURREn:MAXimum?** This command is used to read the maximum current.

**Command Syntax:** PEAK:CURREn:MAXimum?

**Example:** PEAK:CURR:MAX?

**Return Parameters:** <NR2>

**PEAK:CURREn:MINimum?** This command is used to read the minimum current.

**Command Syntax:** PEAK:CURREn:MINimum?

**Example:** PEAK:CURR:MIN?

**Return Parameters:** <NR2>

## 5.11. TWaveform Transient Waveform Grab Command

**TWAVeform** This command can be used to grab the transient voltage and current waveform when the current changes from Ia to Ib.

**TWAVeform[:STATe]** This command is used to start or stop the transient waveform grab.

**Command Syntax:** TWAVeform[:STATe] <bool>

**Example:** TWAV ON

**TWAVeform:IA** This command is used to set Ia.

**Command Syntax:** TWAVeform:IA <Nrf+>

**Example:** TWAV:IA 1

**TWAVeform:IB** This command is used to set Ib.

**Command Syntax:** TWAVeform:IB <Nrf+>



|                           |  |
|---------------------------|--|
| <b>Example:</b>           | TWAV:IA 3  |
| <b>TWAVeform:TINTval</b>  | This command is used to set the sampling interval. Range: 10us ~ 1ms.        |
| <b>Command Syntax:</b>    | TWAVeform:TINTval <Nrf+>   |
| <b>Example:</b>           | TWAV:TINT 0.00001                      Sampling interval: 10us               |
| <b>TWAVeform:POINts</b>   | This command is used to set the number of the sampling points. Range: 2~4096 |
| <b>Command Syntax:</b>    | TWAVeform:POINts <Nrf+>  |
| <b>Example:</b>           | TWAV:POIN 100                      No. of sampling points: 100 points.       |
| <b>TWAVeform:VOLTage?</b> | This command is used to read the voltage waveform data.                      |
| <b>Command Syntax:</b>    | TWAVeform:VOLTage?   |
| <b>Example:</b>           | TWAV:VOLT?   |
| <b>TWAVeform:CURREnt?</b> | This command is used to read the current waveform data.                      |
| <b>Command Syntax:</b>    | TWAVeform:CURREnt?   |
| <b>Example:</b>           | TWAV:CURREnt?  |

## **Certification & Guarantee**

JT632xA series programmable DC electronic load meet its published specifications at time of shipment from the factory.

## **Warranty**

This instrument product is warranted against defects in material and workmanship for a period of one year from date of delivery.

## **Maintenance Service**

This product must be returned to maintenance department designated by our company for repairing. Customer shall prepay shipping charges (and shall pay all duty and taxes) for products returned to the supplier for warranty service. Except for products returned to customer from another country, supplier shall pay for return of products to customer.

## **Limitation of Warranty**

The foregoing warranty shall not apply to

1. Defects resulting from improper or inadequate maintenance by the Customer,
2. Unauthorized modification or misuse,
3. Operation outside of the environmental specifications for the product, or improper site preparation and maintenance.
4. Defects resulting from the circuit installed by clients themselves

## **Attention**

No inform will be given for any changes in the content of the user's guide. Jartul Electronics company reserves the right to interpret.